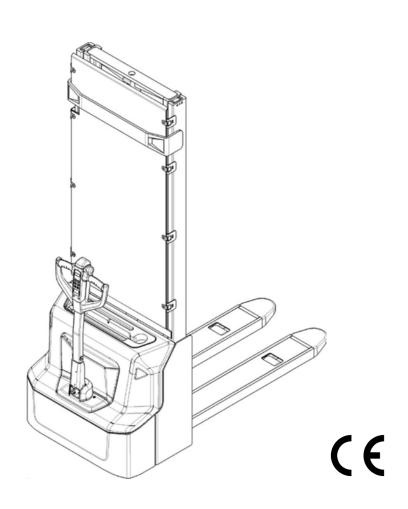
# 12ES-XB, XN Electric Pallet Truck Service Manual



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#### 1 Overview

#### 1-1 How to use this manual

#### 1-1-1 Build this manual

This service manual provides information service engineers and technicians required for vehicle maintenance; it does not contain vehicle operating instructions.

The introductory part of this manual provides an overview of the functions of the vehicle, with particular attention to its different components. You can find each part in the main body of this manual, which provides more specific and detailed information, including schematic diagrams of vehicle components, working methods, inspection contents, repair procedures, and data and information required for repair and maintenance.

To help readers quickly and easily find the services and training information they need, these chapters are based on The different systems included in the vehicle are classified (see the table below).

| Section | Title              |  |
|---------|--------------------|--|
| 1       | general            |  |
| 2       | electronic system  |  |
| 3       | Drive/brake system |  |
| 4       | Hydraulic system   |  |
| 5       | Hydraulic system   |  |
| 6       | steering system    |  |
| 7       | Schematic diagram  |  |
| 8       | other              |  |
| 9       | Charger            |  |

#### 1-1-2 Warning label definition

This manual uses the following three warning labels: "Danger", "Warning" and "Caution". Each label is designed to show the reader the severity and nature of the potential hazards, the consequences, and preventive measures to prevent the hazards. You will find these labels throughout this manual. Make sure you pay attention to them carefully, as they are included for your safety.

| ⚠ Danger                                   |
|--|
| This signs represents a dangerous          |
| situation that could result in death o     |
| serious injury if not avoided              |
| 100 1000                                   |
| ▲ Warning                                  |
| This signs represents a dangerous          |
| situation that could result in death or    |
| serious injury if not avoided              |
|  |
| ▲ Note                                     |
| The label indicates a dangerous situation  |
| that could result in minor injuries if not |
| avoided                                    |

# 1-2 vocabulary

# The following are the terms and descriptions used in this service manual

| Item              | Descriptions  |
|-------------------|---|
| Accelerator       | A device that converts mechanical motion to an analog voltage mode and transmit to  |
|                   | a controller to control the speed at which a vehicle is driven  |
| Actuator          | A device (e.g. a hydraulic cylinder and motor) that converts hydraulic power into   |
|                   | mechanical force and motion.  |
| Ampere (A)        | A measurement unit of current. The current of a voltage passing through an ohmic resistor.                                |
| Battery           | Two or more batteries which are inter-connected with each other to provide current.                                       |
| Coulomb meter     | (Battery Discharge Indicator) an electrically controlled display that shows the operator the current charge of a battery. |
| Bus bar           | A re-conducting conductor that wired to other smaller conductors  |
| Communication     | CAN (Controller Area Network) is the standard for communication among   |
| Modes             | microcontrollers and/or devices.  |
| Condenser         | A device for short-time electrical energy storage.  |
| Goods Holder      | A supporting structure on which a fork is mounted   |
| Check Valve       | A valve that allows oil to flow in one direction rather than in the other   |
| Circuit           | A path along which current can travel from the positive (+) side of the source to the                                     |
|                   | negative (-) side. This can be obtained with wires and electrical components.   |
| Connector         | A part of a wire assembly or harness wired to another wire assembly or harness to   |
|                   | for an easier Disassembly and Assembly operation.   |
| Co-contactor      | A switch, relay, or part of a contactor that opens or closes a circuit  |
| Components of     | An electrical element consisting of an electromagnetic coil and a set of heavy contact                                    |
| Co-contactor      | tips, which controls current flow through the coil, create a  |
|                   | magnetic field, and close or open contact tips  |
| Coil of           | An electromagnet used to open or close contact tips in a contactor component.   |
| Co-contactor      |   |
| Control Valve     | A valve unit includes multiple directional blocks, each of which has a corresponding actuator                             |
| Counterweight     | The weight mounted on the back of the forklift to ensure a stable status, especially when lifting heavy loads             |
| Current Limiting  | The maximum permissible armature current of the stopped drive motor during the pulse.                                     |
| Oil Cylinder      | A container that maintains pressurized oil and converts hydraulic power into rectilinear motion                           |
| DC-DC             | A device that converts a high-voltage DC onto a low-voltage DC.   |
| Convertor         |   |
| Diode             | A semiconductor device that allows current to flow from the anode to the cathode in one direction                         |
| Directional Valve | A valve that directs the flow of oil according to the position of the valve element.                                      |
| Instrument        | An electrical device that converts voltage input into an visual output.   |

| Drive Axle      | A device that receives power from a driving motor  |
|-----------------|--|
| Driving         | A control device to drive an electric motor, which includes an inverter and a logic      |
| Controller      | circuit.   |
| Handheld        | A maintenance tool program to calibrate and diagnose CURTIS controllers of trucks.       |
| programmer      |  |
| Parking Brake   | A pair of brakes that electromagnetically activate their respective motors upon the      |
|                 | stationary of the vehicle.   |
| Encoder         | A device that detects the direction and speed of a motor to produce a pulse signal.      |
| Fan             | A device that generates an airflow to cool an electric motor and a controller            |
| Filter          | A mechanical device used to accommodate a filter element, or a filter device used to     |
|                 | prevent contamination flow through a system  |
| Flow Protector  | A valve that prevents the hydraulic oil extraction of the control valve from the lifting |
|                 | cylinder when the hydraulic line breaks unexpectedly, which prevents the backstay        |
|                 | from dropping suddenly.  |
| Flow Regulator  | A valve that reduces the pressure by limiting the flow of a hydraulic line               |
| Pallet Fork     | L shape rod for cargo pickup   |
| Friction Plate  | When meshing with helical gears, the friction disc stops the drive shaft movement        |
|                 | when it is compressed by the steel plate   |
| Fuse            | A component of a circuit that opens upon an over large current flowing through a         |
|                 | given part of the circuit  |
| Fixture         | A fitting o secure an assembly consisting of two or more wires                           |
| Radiator        | A mounting frame for cooling semiconductors.   |
| Hydraulic       | A hydraulic element circuit to convey oil pressure                                       |
| System          |  |
| Hydraulic Oil   | A chamber for the oil storage in a hydraulic system                                      |
| Tank            |  |
| Mandatory Sign  | A symbol indicating the state of a vehicle when it is on or flashing.                    |
| Main Hydraulic  | A gear pump uses mechanical power from an electric motor to pressurize the oil           |
| Pump            | stored in a tank and distribute to various actuators                                     |
| Mast            | The front vertical structure of the forklift extends and retracts to lift and lower the  |
|                 | load.  |
| Master Cylinder | The hydraulic cylinder which is responsible for the start-up of the driving brake        |
| Needle Valve    | A valve to lower the backstay manually when the lifting lever is not available.          |
| Normal State    | A term used with switches or relays. Their "normal state" means that they are not        |
|                 | under any control of stress, temperature, pressure or electricity.                       |
| $Ohm\ (\Omega)$ | A resistance unit. The resistance will be such that one volt shall push one ampere of    |
|                 | current through it only.   |
| Open Circuit    | A connection or component of a circuit without continuity.                               |
| Hole            | A limited passage in a hydraulic circuit, including a limited flow or pressure           |
|                 | generation in a given chamber(e.g. a small bore).  |
| Overload        | A condition that the existing voltage or current is greater than the capacity of a given |
|                 | circuit or component.  |
| Piston Rod      | A part that push oil into the cylinder chamber   |
| Suffocated      | The part of an electric brake in which the current generated is directed back to the     |
|                 | armature.  |

| Pressure a fluid force as per unit area Proximity A sensor which can detect the presence of objects nearby without any physical contact.  Pump Controller Unit A control device for a hydraulic motor, which includes an inverter and a logic circuit. Safety Valve A valve that limits the pressure of the hydraulic system by releasing excess oil Resistance A component made of a material with a specific current impedance.  Return Filter A filter to collect contaminants in oil returned to a hydraulic tank Rotor A part of rotating motor.  Outline A bar chart of an electrical or electronic component that uses symbols to show the individual components as well as how the wires and connectors work electrically Serial Port A port that communicates one-to-one with the controller.  Short Circuit An unwanted electrical connection between two or more components.  Socket The male contact of the connector which slides over the male contact of the other connector (pin).  Magnetic Valve A directional valve that moves the valve element when the magnetic coil is equipped with a magnetic valve.  Solid State A term that refers to semiconductor components or circuits that wired without moving parts, e.g. diodes and transistors.  Stator A fixing part in the motor  Steering Shaft A column that connects the steering wheel to the steering gear to allow the operator to use steering wheel controller  Hydraulic element loop, including steering unit, circuit and actuator  Steering Gear A axle mounted on the rear wheel of a vehicle  Switch (SW) The component to control a circuit by opening or closing the circuit.  System Electrical components, circuits, and connections that provide power for specific tasks.  Thermal Sensor a sensor activated at a pre-conditioned temperature.  USB A connecting device providing a power supply of 5V.  Valve A component that controls the pressure, direction, or velocity of a hydraulic system  A measurement unit of electrodynamic force. A volt is the force that required for an ampere of current to pass through an ohmic |                 |   |
|--|-----------------|---|
| Proximity Detector  Pump Controller contact.  Pump Controller Unit  Safety Valve A control device for a hydraulic motor, which includes an inverter and a logic circuit.  Safety Valve A valve that limits the pressure of the hydraulic system by releasing excess oil  Resistance A component made of a material with a specific current impedance.  Return Filter A filter to collect contaminants in oil returned to a hydraulic tank  Rotor A part of rotating motor.  Outline A bar chart of an electrical or electronic component that uses symbols to show the individual components as well as how the wires and connectors work electrically  Serial Port A port that communicates one-to-one with the controller.  Short Circuit An unwanted electrical connecton between two or more components.  Socket The male contact of the connector which slides over the male contact of the other connector (pin).  A directional valve that moves the valve element when the magnetic coil is equipped with a magnetic valve.  Solid State A term that refers to semiconductor components or circuits that wired without moving parts, e.g. diodes and transistors.  Stator A column that connects the steering wheel to the steering gear to allow the operator to use steering wheel controller  Steering Shaft C sax wheel controller  Steering Gear A axle mounted on the rear wheel of a vehicle  Switch (SW) The component to control a circuit by opening or closing the circuit.  System Electrical components, circuits, and connections that provide power for specific tasks.  Thermal Sensor a sensor activated at a pre-conditioned temperature.  USB A connecting device providing a power supply of 5V.  Valve A component that controls the pressure, direction, or velocity of a hydraulic system where of unity of power measurement. The power for one volt to push one ampere of current through an ohmic resistor.  The outcomes of amperage (current) multiplied by volts (voltage) is watts (power).  Wire A path of conductors to provide for current flow in and out of different electrical co | Power Socket    | A connecting socket that installed on the forklift.                                     |
| Detector Pump Controller Unit A control device for a hydraulic motor, which includes an inverter and a logic circuit.  Safety Valve A valve that limits the pressure of the hydraulic system by releasing excess oil Resistance A component made of a material with a specific current impedance.  Return Filter A filter to collect contaminants in oil returned to a hydraulic tank A part of rotating motor.  Outline A bar chart of an electrical or electronic component that uses symbols to show the individual components as well as how the wires and connectors work electrically Serial Port A port that communicates one-to-one with the controller.  Short Circuit An unwanted electrical connection between two or more components.  Socket The male contact of the connector which slides over the male contact of the other connector (pin).  Magnetic Valve A directional valve that moves the valve element when the magnetic coil is equipped with a magnetic valve.  Solid State A term that refers to semiconductor components or circuits that wired without moving parts, e.g. diodes and transistors.  Stator Steering Shaft A column that connects the steering wheel to the steering gear to allow the operator to use steering wheel controller  Steering System Hydraulic element loop, including steering unit, circuit and actuator  Steering Gear Switch (SW) Flectrical components or circuits, and connections that provide power for specific tasks.  Thermal Sensor  a sensor activated at a pre-conditioned temperature.  Voltage A connecting device providing a power supply of 5V.  Valve A component that controls the pressure, direction, or velocity of a hydraulic system  Voltage A measurement unit of electrodynamic force. A volt is the force that required for an ampere of current to pass through an ohmic resistor in a circuit.  Watt A unit of power measurement. The power for one volt to push one ampere of current through an ohmic resistor.  The outcomes of amperage (current) multiplied by volts (voltage) is watts (power).  A path of conductors to provide  | Pressure        | a fluid force as per unit area  |
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| Safety Valve Resistance Return Filter Rotor A part of rotating motor.  Outline A part of rotating motor.  Outline A port that components as well as how the wires and connectors work electrically Serial Port Short Circuit An unwanted electrical connection between two or more components.  The male contact of the connector which slides over the male contact of the other connector (pin).  Magnetic Valve Solid State A climant at refers to semiconductor components or circuits that wired without moving parts, e.g. diodes and transistors.  Stator Steering Shaft A column that connects the steering wheel to the steering gear to allow the operator to use steering wheel controller  Switch (SW) The component to control a circuit by opening or closing the circuit.  System USB A connecting device providing a power supply of 5V.  Valve A component that controls the pressure, direction, or velocity of a hydraulic system Watt A unit of power measurement. The power for one volt to push one ampere of current through an ohmic resistor.  The outcomes of amperage (current) multiplied by volts (voltage) is watts (power).  Wiring Diagram A visualized figure that represents a component in the way it actually looks, which is used to the connections between them.  | Pump Controller | A control device for a hydraulic motor, which includes an inverter and a logic circuit. |
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| Serial Port A port that communicates one-to-one with the controller.  Short Circuit An unwanted electrical connection between two or more components.  The male contact of the connector which slides over the male contact of the other connector (pin).  Magnetic Valve A directional valve that moves the valve element when the magnetic coil is equipped with a magnetic valve.  Solid State A term that refers to semiconductor components or circuits that wired without moving parts, e.g. diodes and transistors.  Stator a fixing part in the motor  Steering Shaft A column that connects the steering wheel to the steering gear to allow the operator to use steering wheel controller  Steering Gear Hydraulic element loop, including steering unit, circuit and actuator  Steering Gear A axle mounted on the rear wheel of a vehicle  Switch (SW) The component to control a circuit by opening or closing the circuit.  Electrical components, circuits, and connections that provide power for specific tasks.  Thermal Sensor A connecting device providing a power supply of 5V.  Valve A component that controls the pressure, direction, or velocity of a hydraulic system  Voltage A measurement unit of electrodynamic force. A volt is the force that required for an ampere of current to pass through an ohmic resistor in a circuit.  Watt A unit of power measurement. The power for one volt to push one ampere of current through an ohmic resistor.  The outcomes of amperage (current) multiplied by volts (voltage) is watts (power).  Wire A path of conductors to provide for current flow in and out of different electrical components.  Wiring Diagram A visualized figure that represents a component in the way it actually looks, which is used to show the locations of components, and the connections between them.  | Outline         | A bar chart of an electrical or electronic component that uses symbols to show the      |
| Short Circuit Socket The male contact of the connector which slides over the male contact of the other connector (pin).  Magnetic Valve A directional valve that moves the valve element when the magnetic coil is equipped with a magnetic valve.  Solid State A term that refers to semiconductor components or circuits that wired without moving parts, e.g. diodes and transistors.  Stator Steering Shaft A column that connects the steering wheel to the steering gear to allow the operator to use steering wheel controller  Steering Gear Switch (SW) Hydraulic element loop, including steering unit, circuit and actuator  Steering Gear Switch (SW) The component to control a circuit by opening or closing the circuit.  System Electrical components, circuits, and connections that provide power for specific tasks.  Thermal Sensor USB A connecting device providing a power supply of 5V.  Valve A component that controls the pressure, direction, or velocity of a hydraulic system  Voltage A measurement unit of electrodynamic force. A volt is the force that required for an ampere of current to pass through an ohmic resistor in a circuit.  Watt A unit of power measurement. The power for one volt to push one ampere of current through an ohmic resistor.  The outcomes of amperage (current) multiplied by volts (voltage) is watts (power).  Wire A path of conductors to provide for current flow in and out of different electrical components.  Wiring Diagram A visualized figure that represents a component in the way it actually looks, which is used to show the locations of components, and the connections between them.  |                 | individual components as well as how the wires and connectors work electrically         |
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| Steering System Hydraulic element loop, including steering unit, circuit and actuator  Steering Gear A axle mounted on the rear wheel of a vehicle  Switch (SW) The component to control a circuit by opening or closing the circuit.  System Electrical components, circuits, and connections that provide power for specific tasks.  Thermal Sensor a sensor activated at a pre-conditioned temperature.  USB A connecting device providing a power supply of 5V.  Valve A component that controls the pressure, direction, or velocity of a hydraulic system  Voltage A measurement unit of electrodynamic force. A volt is the force that required for an ampere of current to pass through an ohmic resistor in a circuit.  Watt A unit of power measurement. The power for one volt to push one ampere of current through an ohmic resistor.  The outcomes of amperage (current) multiplied by volts (voltage) is watts (power).  Wire A path of conductors to provide for current flow in and out of different electrical components.  Wiring Diagram A visualized figure that represents a component in the way it actually looks, which is used to show the locations of components, and the connections between them.  | Stator          | a fixing part in the motor  |
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| Steering Gear Switch (SW) The component to control a circuit by opening or closing the circuit.  System Electrical components, circuits, and connections that provide power for specific tasks.  Thermal Sensor a sensor activated at a pre-conditioned temperature.  USB A connecting device providing a power supply of 5V.  Valve A component that controls the pressure, direction, or velocity of a hydraulic system  Voltage A measurement unit of electrodynamic force. A volt is the force that required for an ampere of current to pass through an ohmic resistor in a circuit.  Watt A unit of power measurement. The power for one volt to push one ampere of current through an ohmic resistor. The outcomes of amperage (current) multiplied by volts (voltage) is watts (power).  Wire A path of conductors to provide for current flow in and out of different electrical components.  Wiring Diagram A visualized figure that represents a component in the way it actually looks, which is used to show the locations of components, and the connections between them.   |                 | to use steering wheel controller  |
| Switch (SW)  The component to control a circuit by opening or closing the circuit.  System  Electrical components, circuits, and connections that provide power for specific tasks.  Thermal Sensor  a sensor activated at a pre-conditioned temperature.  USB  A connecting device providing a power supply of 5V.  Valve  A component that controls the pressure, direction, or velocity of a hydraulic system  Voltage  A measurement unit of electrodynamic force. A volt is the force that required for an ampere of current to pass through an ohmic resistor in a circuit.  Watt  A unit of power measurement. The power for one volt to push one ampere of current through an ohmic resistor.  The outcomes of amperage (current) multiplied by volts (voltage) is watts (power).  Wire  A path of conductors to provide for current flow in and out of different electrical components.  Wiring Diagram  A visualized figure that represents a component in the way it actually looks, which is used to show the locations of components, and the connections between them.   | Steering System | Hydraulic element loop, including steering unit, circuit and actuator                   |
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| USB A connecting device providing a power supply of 5V.  Valve A component that controls the pressure, direction, or velocity of a hydraulic system  Voltage A measurement unit of electrodynamic force. A volt is the force that required for an ampere of current to pass through an ohmic resistor in a circuit.  Watt A unit of power measurement. The power for one volt to push one ampere of current through an ohmic resistor.  The outcomes of amperage (current) multiplied by volts (voltage) is watts (power).  Wire A path of conductors to provide for current flow in and out of different electrical components.  Wiring Diagram A visualized figure that represents a component in the way it actually looks, which is used to show the locations of components, and the connections between them.  |                 | tasks.  |
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| ampere of current to pass through an ohmic resistor in a circuit.  Watt A unit of power measurement. The power for one volt to push one ampere of current through an ohmic resistor. The outcomes of amperage (current) multiplied by volts (voltage) is watts (power).  Wire A path of conductors to provide for current flow in and out of different electrical components.  Wiring Diagram A visualized figure that represents a component in the way it actually looks, which is used to show the locations of components, and the connections between them.   | Valve           | A component that controls the pressure, direction, or velocity of a hydraulic system    |
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| through an ohmic resistor. The outcomes of amperage (current) multiplied by volts (voltage) is watts (power).  Wire A path of conductors to provide for current flow in and out of different electrical components.  Wiring Diagram A visualized figure that represents a component in the way it actually looks, which is used to show the locations of components, and the connections between them.   |                 | ampere of current to pass through an ohmic resistor in a circuit.                       |
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| Wire A path of conductors to provide for current flow in and out of different electrical components.  Wiring Diagram A visualized figure that represents a component in the way it actually looks, which is used to show the locations of components, and the connections between them.  |                 | through an ohmic resistor.  |
| components.  Wiring Diagram A visualized figure that represents a component in the way it actually looks, which is used to show the locations of components, and the connections between them.   |                 | The outcomes of amperage (current) multiplied by volts (voltage) is watts (power).      |
| Wiring Diagram  A visualized figure that represents a component in the way it actually looks, which is used to show the locations of components, and the connections between them.   | Wire            | A path of conductors to provide for current flow in and out of different electrical     |
| used to show the locations of components, and the connections between them.  |                 | components.   |
| and the connections between them.  | Wiring Diagram  |   |
|  |                 | ·   |
| Zener Diode A special diode to regulate voltage or protect a system from overvoltage.  |                 |   |
|  | Zener Diode     | A special diode to regulate voltage or protect a system from overvoltage.               |

# 1-3 Appearance and specifications

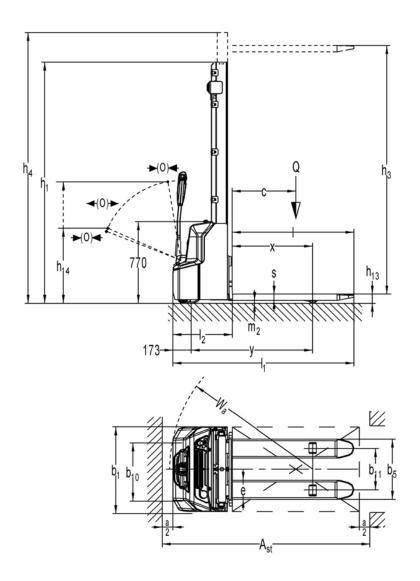


Table 1:Main technical data of the standard version

|                     | Type sheet for industrial truck acc. to VDI 2198 |   |                  |                   |           |                      |  |
|---------------------|--|---|------------------|-------------------|-----------|----------------------|--|
|                     | 1.2  | Manufacturer`s type designation                   |                  | 12ES-XN           | 12ES-XB   | 12ES-XN(EN1175:2020) |  |
| 논                   | 1.3  | Power(battery ,die sel, petrol, gas, manual)      |                  | Battery           |           |                      |  |
| g ma                | 1.4  | Operator type                                     |                  | Pedestrian        |           |                      |  |
| Distinguishing mark | 1.5  | Load Capacity / rated load                        | Q(t)             | 1.2               |           |                      |  |
| istingı             | 1.6  | Load center distance                              | c(m<br>m)        |                   | 600       |                      |  |
| ΙŌ                  | 1.8  | Load<br>distance ,center of<br>drive axle to fork | x(m<br>m)        | 760               |           | 710                  |  |
|                     | 1.9  | Wheelbase   | Y(m<br>m)        | 1147              |           | 1097                 |  |
|                     | 2.1  | Service weight                                    | kg               | 585               | 650       | 620                  |  |
| Weight              | 2.2  | Axle loading, laden front/rear                    | kg               | 560 / 1225        | 530/ 1320 | 520/ 1300            |  |
| ^                   | 2.3  | Axle loading,<br>unladen(front/rear)              | kg               | 440 / 145         | 450 / 200 | 440 / 180            |  |
|                     | 3.1  | Tires   |                  | Polyurethane (PU) |           |                      |  |
|                     | 3.2  | Tire size, front                                  | ∅ x<br>w<br>(mm) | Ф210 х 70         |           | Ф210 х 75            |  |
| ssis                | 3.3  | Tire size, rear                                   | ∅ x<br>w<br>(mm) |                   | Ф84 х 93  |                      |  |
| ires, chassis       | 3.4  | Additional wheels(dimension s)                    | ∅ x<br>w<br>(mm) |                   | Ф100 x 50 |                      |  |
| Tir                 | 3.5  | Wheels, number front/rear(x=driven wheels)        |                  | 1x + 1 / 2        |           |                      |  |
|                     | 3.6  | Track, front                                      | b10<br>(mm)      |                   | 5         | 550                  |  |
|                     | 3.7  | Track, rear                                       | b11<br>(mm)      | 400 / 515         |           |                      |  |
|                     | 4.2  | Lowered mast height                               | h1<br>(mm)       |                   | 2         | 280                  |  |
|                     | 4.3  | Free Lift height                                  | h2<br>(mm)       |                   |           | -                    |  |
| ions                | 4.4  | Lift height                                       | h3<br>(mm)       | 3514              |           |                      |  |
| Dimensions          | 4.5  | Extended mast height                              | h4<br>(mm)       | 4037              |           |                      |  |
| Dir                 | 4.9  | Height of tiller in drive position min./ max.     | h14<br>(mm)      | 710 / 1150        |           |                      |  |
|                     | 4.1<br>5   | Height, lowered                                   | h13 (mm) 86 90   |                   |           | 90                   |  |

|                    | 4.1<br>9 | Overall length                                     | 11<br>(mm)    | 1710             |                           |           |  |
|--------------------|----------|--|---------------|------------------|---------------------------|-----------|--|
|                    | 4.2<br>0 | Length to face of forks                            | 12<br>(mm)    | 560              |                           |           |  |
|                    | 4.2<br>1 | Overall width                                      | b1<br>(mm)    | 800              |                           |           |  |
|                    | 4.2<br>2 | Fork dimensions                                    | s/e/l<br>(mm) |                  | 30 / 1150                 |           |  |
|                    | 4.2<br>5 | Distance between fork-arms                         | b5<br>(mm)    |                  | ) / 685                   |           |  |
|                    | 4.3<br>2 | Ground clearance,<br>center of<br>wheelbase        | m2<br>(mm)    | 26               |                           | 24        |  |
|                    | 4.3<br>3 | Aisle width for pallets 1000X1200 crossways        | Ast<br>(mm)   | 2197             |                           | 2167      |  |
|                    | 4.3<br>4 | Aisle width for pallets 800X1200 lengthways        | Ast<br>(mm)   | 2145             |                           | 2133      |  |
|                    | 4.3<br>5 | Turning radius                                     | Wa<br>(mm)    | 1350             |                           | 1300      |  |
| а                  | 5.1      | Travel speed,<br>laden/ unladen                    | Km/h          | 4.5 / 4.7        |                           | 4.2 / 4.5 |  |
| Performance data   | 5.2      | Lift speed, laden/<br>unladen                      | m/s           | 0.12 / 0.19      |                           |           |  |
| manc               | 5.3      | Lowering speed, laden/ unladen                     | m/s           | 0.13 / 0.11      |                           |           |  |
| Perfor             | 5.8      | Max. gradeability,<br>laden/ unladen               | %             | 5/10             |                           |           |  |
|                    | 5.1<br>0 | Service brake                                      |               |                  | Electro                   | magnetic  |  |
|                    | 6.1      | Drive motor rating S2 60min                        | kW            |                  | 0                         | 0.65      |  |
|                    | 6.2      | Lift motor rating at S3 10%                        | kW            |                  | 2                         | 2.2       |  |
| Engine-            | 6.3      | Battery acc. to DIN 43531/35/36 A, B, C, no        |               |                  |                           | no        |  |
| Electrical Engine- | 6.4      | Battery voltage,<br>nominal capacity<br>K5         | V/Ah          | 24 / 60          | 2 x 12 / 85 <sup>1)</sup> | 24 / 60   |  |
|                    | 6.5      | Battery weight                                     | kg            | 19               | 2 x 27 <sup>2)</sup>      | 17        |  |
|                    | 6.6      | Energy<br>consumption acc:<br>to VDI cycle         | Kwh/<br>h     | 0.8 0.6          |                           | 0.6       |  |
| ınal               | 8.1      | Type of drive control                              |               | AC-speed control | DC                        |           |  |
| Additional         | 8.4      | Sound level at<br>driver`s ear acc. to<br>EN 12053 | dB(A          | <70              |                           |           |  |

1) Optional: 2x12V/106Ah 2) 2x12V/106Ah : 2 x 34kg

#### 12ES-XB/N

| Tuno              | Lowered mast height | Free Lift height | Lift height | Extended mast height |
|-------------------|---------------------|------------------|-------------|----------------------|
| Type              | h1(mm)              | h2(mm)           | h3(mm       | h4(mm)               |
| One stage         | 1930                | 1514             | 1514        | 1930                 |
| mast              | 2330                | 1914             | 1914        | 2330                 |
| Two stage         | 1930                | -                | 2814        | 3337                 |
| Two stage<br>mast | 2080                | -                | 3114        | 3637                 |
| เมลรเ             | 2280                | -                | 3514        | 4037                 |

#### 12ES-XB/N(EN1175:2020)

| Turn o    | Lowered mast height | Free Lift height | Lift height | Extended mast height |
|-----------|---------------------|------------------|-------------|----------------------|
| Туре      | h1(mm)              | h2(mm)           | h3(mm       | h4(mm)               |
| One stage | 1930                | 1514             | 1514        | 1930                 |
| mast      | 2330                | 1914             | 1914        | 2330                 |
|           | 1780                | -                | 2514        | 3037                 |
| Two stage | 1930                | -                | 2814        | 3337                 |
| mast      | 2080                | -                | 3114        | 3637                 |
|           | 2280                | -                | 3514        | 4037                 |

# **1-4 Overview of Main Components**

# 12ES-XB/XN (EN1175:2020)

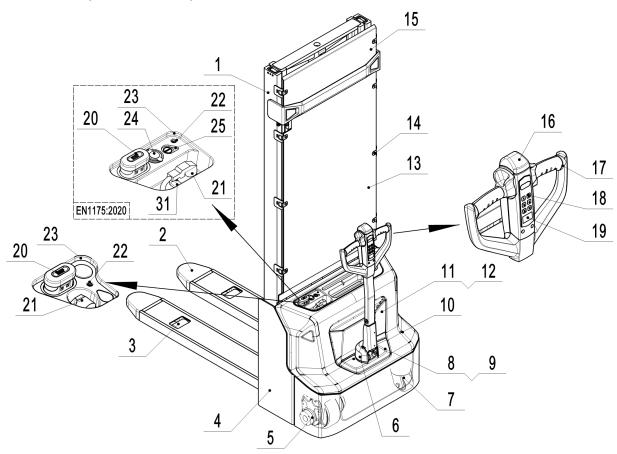


Fig.1: Overview of main components

| 1.Mast assembly               | 11.Panel (folder)        | 21.Charging spring line   |
|-------------------------------|--------------------------|---------------------------|
| 2.Pallet frame assembly       | 12.Bottom cover (folder) | 22.Charging indicator     |
| 3.Load-bearing wheel assembly | 13.Protection plate      | 23.Instrument panel       |
| 4.Body assembly               | 14.Spring clips          | 24.USB power supply       |
|                               |                          | (12ES-XN,XB)              |
| 5.Drive wheel assembly        | 15.Protective plate      | 25.Push button switch     |
|                               |                          | (12ES-XN,XB)              |
| 6.Protective cover (handle)   | 16.Belly switch          | 31.Socket                 |
|                               |                          | (12ES-XB, XN EN1175:2020) |
| 7.Balance wheel assembly      | 17.Handle                |                           |
| 8.Lower panel 1 (handle)      | 18.Combination lock      |                           |
| 9.Lower panel 2 (handle)      | 19.Power meter           |                           |
| 10.Housing                    | 20.Emergency stop switch |                           |

#### 1-5 Cautions

The safety section includes the following subsections: general, personal safety, maintenance safety, compressed air hazards, hydraulic oil hazards, mechanical hazards, electrical hazards, and fire and burn hazards. Under each heading are listed the precautions you should take to ensure that you 14 stay safe while working on the vehicle.

Readers are responsible for reading thoroughly, understanding and implementing all the following preventive measures. Please also note that the safety instructions listed below are not only for the safety of the reader, but also for the people around him. Therefore, for your own personal safety and the safety of those around you, please read the following instructions carefully:

#### General

#### Safety instructions

Be familiar with the safety instructions immediately visible on the vehicle. These include warning signs, stickers, engravings, etc. Before operating, lubricating or repairing the vehicle, please write down and read them (see the section "Description of Safety Devices and Warning Labels" in the "Operation Manual").

Ensure that all safety rules, regulations and instructions are followed when performing maintenance. Please pay special attention to the danger warnings in this manual, which will inform you of potentially dangerous situations.

Do not assume that you can perform the steps outlined in this manual based on your previous maintenance experience with similar models. Different models have different weights and specifications, so close attention should be paid to avoid dangerous situations, injuries and/or component damage.

#### **Personal safety**

Do not operate or maintain the vehicle without authorization or training. Do not operate or maintain the vehicle after drinking alcohol or drugs that damage your judgment.

If you have any diseases or conditions that restrict physical activity, do not operate or maintain the vehicle.

#### Description of safety devices and warning labels

A Hanger label

B Warning label

C Load Curve Patch

D Prohibit arm sticker

E nameplate

F Read this note label

G Refill Label

H Prohibit Multiplication of Coordinate Sticks

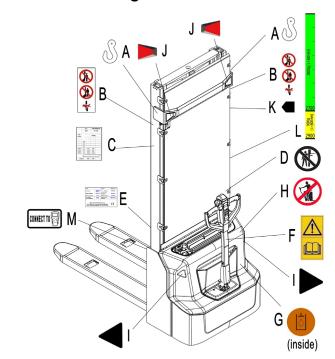
I Warning Label

J Warning Poster

K Height Indicator

L Height Ruler

This stacker crane has a key emergency stop switch (20) that stops all lifting, lowering and driving functions and also disables the electromagnetic brake. After checking the



functions of the controller, unplug this switch to operate this stacker crane. Before operation, manually enter the code to start the vehicle.

If you do not operate the stacker, to prevent unauthorized use, press the emergency stop switch (20) or press the "X" button on the combination lock panel.

This stacker is equipped with a belly switch (16) that allows the vehicle to move away from the operator when the vehicle is moving toward the operator by touching the belly switch within the operating range of the handle.

Also follow the instructions shown on the label and replace it promptly if it is damaged or missing.

#### Assembly/disassembly

Ensure that the assembly/disassembly work site is kept clean, tidy and dry, and keep hand tools clean. When tightening/loosening bolts and nuts, please use a wrench of appropriate size and always pull it toward your body. Using the wrong wrench size or pushing away from the body to loosen/tighten the bolts or nuts may cause accidents due to the sliding of the handle.

If two or more people are working, use signs or signals to communicate so that the work is done in an agile way, as if the work was done by one person.

Reinstall all fasteners using the same parts. If you need to replace any fasteners, please use high-quality fasteners and be careful not to use metric system fasteners mixed with imperial fasteners.

 Model
 12ES-XB/ 3600
 12ES-XN/ 3600

 Packing weight [kg]
 680
 650

 Lifting height
 680
 680

3600

[mm]

3600

Table 2: Test Data

After receipt of our new stacking truck or when a re-adjustment is required, please proceed with the following steps before operating the vehicle (for the first time):

- Check that all parts are included and not damaged
- Installation and charging of batteries (refer to 2-2-3)
- Conduct routine and machine function checks

#### Lifting/ transportation

Check the weight of each component before removing it.

Some components of this vehicle are very heavy and may cause serious injury.

Use proper lifting procedures when removing any component
To avoid back injuries, use a hoist when lifting components weighing
23 kg (50lbs) or more. Make sure all chains, hooks, slings, etc. are
in good condition and of the correct capacity. Make sure that the

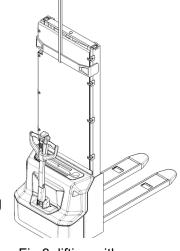


Fig 3: lifting with crane

hooks are properly positioned. The eyebolt should not be loaded sideways during the lifting operation.

Stacking trucks need to be securely fastened to trucks or trucks during transportation.

Lower the forks and park the vehicle safely. As shown in Fig. 4, a special strap for hoisting is used to fix the body, fork and mast, and the other side is fixed to the transport vehicle.

#### Storage/decommissioning

For storage, remove the load, lower the truck to the lowest position, grease all in this handbook mentioned greasing points (regular inspection), and eventually protect the truck against corrosion and dust. Remove the batteries and jack the truck safely, so that there will be no flattening after storage.

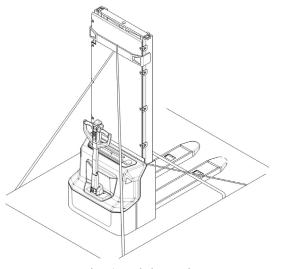


Fig. 4: Fixing point

For final decommissioning hand the truck to a designated recycling company. Oil, batteries and electric components must be recycled due to legal regulations.

#### 1-6 maintenance

#### **Maintenance security**

#### **Pre-maintenance**

Ensure that the vehicle is in a clean, open environment and free from traffic and other people.

Make sure the vehicle is parked safely and that it does not move suddenly. Place wooden props in front and behind the wheels and make sure the parking brake is properly engaged.

Make sure the vehicle is empty and unoccupied, the forks are lowered, all hydraulic controls are in neutral, and the key is switched to OFF. Attach a "do not operate" or similar warning label to the starter switch or control before servicing or repairing the vehicle.

Make sure the tools are in good condition.

The following describes the key items and replaceable parts to be checked during maintenance intervals.

**Note**: Except for the daily inspection by the vehicle driver, all maintenance and repairs should be carried out by qualified and authorized engineers.

**Note**: Careless handling of waste oil will not only harm the environment but also human health. Waste oil should always be placed in a container and disposed of by authorized personnel at designated locations.

#### **Check if necessary**

| item                | Inspection standards and methods  |
|---------------------|---|
| Gear rack roller    | Measure the distance from the bottom of the inner main frame to the bottom of the carriage bearing, Make the inner mast upright, and then adjust the extrusion of the roller. |
| Power module        | Before touching any electrical components, the power module must be fully discharged.   |
| Fuse box            | Check whether the fuse has any removed components and replace it if necessary.  10 A: Key switch  150 A: main fuse  |
| Wheel bolts         | Check whether the wheel bolts and nuts are fixed as follows: Drive tightening torque: 50 Nm   |
| Drive axle gear box | Check the gearbox for lubricating oil  Refill the lubricating oil into the plug opening to check the housing level  |

#### Check every 10 service hours or once a day

|             | -   |
|-------------|---|
| Item        | Inspection standards and methods  |
| Walk around | Check for loose parts and fasteners.  |
|             | Check whether the indicator on the dashboard is abnormal.                             |
|             | Check whether the horn and other alarms are operating normally. Check whether the     |
|             | mast and lifting chain are worn out, and whether the pins/rollers are abnormal.       |
|             | Check the shelf, front fork and accessories for damage and abnormality. Check whether |
|             | the tires, valves and wheels are abnormal.  |
|             | Check the hydraulic system for oil leakage and damage.                                |
|             | Check whether the drive is leaking.   |
| mast        | Lubricate the beam where the rollers are located.                                     |
| Tires       | Check the tires for wear, cuts, grooves and contamination.                            |

#### Check every 500 service hours or 3 months

| Item             | Inspection standards and methods  |
|------------------|---|
| Crosshead roller | Check whether the crosshead roller guard and retainer are damaged.            |
| Mast, chain      | Check whether the lifting cylinder is operating normally.                     |
|                  | Check whether the fork is operating normally.                                 |
|                  | Use a brush to lubricate all chains and check whether their anchor points are |
|                  | abnormal.   |
| Steering shaft   | Lubrication of steering shaft accessories                                     |
| control panel    | Clean the control panel.  |
|                  | Maximum allowable air pressure: 205 kpa (29.7 psi)                            |
| accelerator      | Check the tightness of the accelerator switch mounting bracket, and repair as |
|                  | needed.   |
|                  | Check for loose wiring and fix it if necessary.                               |
| Hydraulic oil    | Check the hydraulic oil level and refill as needed                            |

#### Check every 1,000 service hours or 6 month

| Item                 | Inspection standards and methods   |
|----------------------|--|
| Drive and hydraulic  | Dust and inspect the drive motor and electrical parts area.                |
| pump motor           | Maximum allowable air pressure: 205 kpa (29.7 psi)                         |
| Hydraulic oil return | Replace the oil return filter in the hydraulic oil tank.                   |
| filter               |  |
| Tires                | Inspect tires for wear, cuts, grooves, contaminants, etc.                  |
|                      | Check wheel parts for cracks, wear, damage, corrosion, etc.                |
|                      | Drive wheel standard torque: 50 N-m  |
| Lifting chain        | Performing a lift chain wear test by measuring the wear of links and pins. |

#### Check every 2,000 service hours or once a year

| Item             | Inspection standards and methods   |
|------------------|--|
| Hydraulic system | Replace hydraulic oil and filter.  |
| Basic            | Under normal circumstances, regular inspections are carried out at least every 12      |
| maintenance      | months. If you work for a long time or under a heavy load, perform regular             |
|                  | inspections for 6 months. If you find any of the following conditions, please replace: |
|                  | Healing of cracks on forks, welding, brackets, etc.                                    |

#### 1-7 lubricating oil

The following is a detailed description of the required lubricant and the parts to be lubricated.

#### 1-7-1 Lubricant specifications

The following lubricants are recommended for chains and connecting rods:

| Item | Specification             |
|------|---------------------------|
| 1    | DIN 51825 Standard grease |

#### 1-7-2 Hydraulic oil(HYDO)

The hydraulic oil should have anti-wear, anti-foam, anti-rust and anti-oxidant additives for heavy-duty use as stated by the petroleum supplier. The ISO viscosity grade is usually No. 32.

Note: The correct hydraulic oil should be used to achieve the maximum service life and performance of hydraulic system components. It is recommended to use the above hydraulic oils in most hydraulic and hydraulic systems.

If the hydraulic oil becomes turbid, it means that water or air has entered the system. Water or air in the system will cause the pump to malfunction. Drain all hydraulic oil, re-tighten all hydraulic suction pipe clamps, then clean and refill the system.

#### **Lubricating point**

Lubricate marked points according to maintenance list. The required grease specification is: DIN 51825 standard grease.

- 1.Load bearing wheel bearing
- 2.Mast
- 3.Chain
- 4. Steering bearing
- 5.Gear box
- 6.Balance wheel bearing

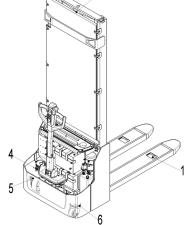


Fig. 5: Lubricating point

#### Check and refill the hydraulic oil

Hydraulic oil type recommended according to temperature is:

| Tydradilo on type recommended decording to temperature is: |                                |                   |  |  |
|--|--------------------------------|-------------------|--|--|
| Environment  | –5°C~25°C                      | >25°C             |  |  |
| temperature  |                                |                   |  |  |
| Type   | HVLP 32, DIN 51524             | HLP 46, DIN 51524 |  |  |
| Viscosity  | 28.8-35.2                      | 41.4-47           |  |  |
| Amount   | 5L (depends on specific model) |                   |  |  |

Waste material like oil, used batteries or other must be probably disposed and recycled according to the national regulations and if necessary brought to a recycling company.

Fuel Tank



The oil level in the oil tank should be between min and max marks with fully lowered forks. If necessary add oil at the filling point.



#### 1-8 Disassembly/assembly instructions

The disassembly/assembly part includes the following subsections: preparations before disassembly, inspection and testing before disassembly, precautions during disassembly, precautions after disassembly, precautions during assembly, handling of general parts, and hydraulic pipeline accessories. Precautions to be taken to perform disassembly/assembly work correctly are listed under each heading.

#### Preparation before disassembly

Remove dust and pollutants from the vehicle before sending it to a repair center. Dust or contaminants entering the repair center may stain the components and enter them to cause damage.

Electric vehicles operate based on electrical systems. Do not let any water enter the system.

To avoid unnecessary disassembly work, prepare the necessary tools, place the boxes for the parts, and give priority to ensuring the cleanliness of the site

#### Check and test before disassembly

Before starting disassembly, be sure to record any problems. This prevents unnecessary disassembly, loss of replacement parts, and repeated failures caused by the same problem

To prevent malfunction, please record the malfunction and the parts required for replacement. Also make sure to check and record the following information:

Vehicle model, serial number and business hours

The reason why the vehicle needs to be disassembled.

Check the symptom, location and cause of the malfunction.

(If necessary, reproduce the same failure).

Check if any parts are inappropriate.

Check for damage or loose parts.

If possible, check the maintenance of the vehicle o

Precautions when disassembling

#### Disassemble

Determine the assembly method of the parts (front/rear, left/right and top/bottom connection) to determine the disassembly sequence.

Before starting to disassemble the parts, pay attention to the connection points of the parts and mark them with arrows to avoid incorrect placement of the parts during assembly.

Use the right tools to delete specific parts.

If you have not removed any parts, even the mounting bolts and nuts, do not use excessive force. Check and find the reason.

Put the disassembled parts on one side in the order of disassembly, and put labels or marks on the parts with similar appearance.

Store bolts, nuts and other common parts in an orderly manner.

Check and test during disassembly

Sometimes the cause of the failure will be discovered during the disassembly process. Therefore, it is very important to carefully check the condition of the friction surface and the contact parts.

During the disassembly process, measure and record the gap, deformation, projection and other factors that may cause the failure.

#### Keep the gap

Ensure that the installed gaskets and washers produce the required specified clearance value

#### Remove press parts

Remove any dents or marks caused by hammering and polishing the area.

If you loose any press-fitted parts, please determine and eliminate the cause to avoid problems during the assembly process.

#### Disassemble the bearing

Do not use force to disassemble the bearing, but use a bearing puller.

#### **Precautions after disassembly**

#### Clean

Clean the disassembled parts and keep them away from contaminants.

Pay special attention to removing contaminants from the oil pipeline or component pipeline. 21

When cleaning special parts, increase the number of detergent containers and clean them several times.

Kerosene or neutral anhydride diesel oil is suitable for cleaning the viscous oil in the bearing.

When using hazardous chemical cleaners, please be careful not to contact your skin or eyes. Use designated containers to dispose of used oil at designated locations.

#### dust-proof

Use a dust cover to place the cleaned parts in a place free of dust and contaminants, and block the ends of all pipes. Before installing again, any parts you may store must be rust-proof.

#### Precautions during assembly

#### Parts installation

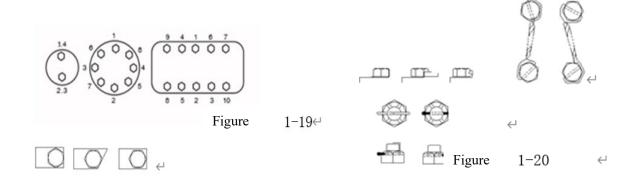
Keep all parts clean before assembly. Check the surface for defects and repair as needed. Make sure not to smear or rub the surface on any part, otherwise the service life of the part may be shortened. Before starting the assembly, use a cleaning agent to remove the rust inhibitor from the components. Before starting the assembly, determine the mark that will assemble the parts together.

Use press-fit tools to assemble bearings, bushings and oil seals, and use designated tools to process specific parts. Before press-fitting parts, lubricate their surfaces with lubricating oil.

#### Tighten the bolts and nuts

To ensure the even torque of the bolts and nuts, tighten them in the order shown in Figure 1-19, and then tighten the other side on the other side. This method is called the "template method" and it gradually repeats loosening and tightening to ensure uniform contact.

Use the wires, split pins, lock washers or other parts shown in Figure 1-20 to fix bolts, nuts or other important fasteners that cannot be visually inspected



#### **Check during assembly**

in each step of the assembly process, check and record each part number

#### Reassemble the gasket

Install gaskets and washers in the same positions as before, and then check if the gap is correct.

#### Assembly adjustment link

If there is no need to adjust, please assemble them to the same length as before

#### Assemble press parts

Repair scratches and dents as needed, and keep parts clean before insertion. Note that press-fit parts that are not sufficiently tightened may loosen.

#### Assemble the key and keyway

Check whether the keyway and key are loose and whether they are in contact with the key head. If the key head touches the keyway, remove the remaining part of the key head.

Handling general parts

#### Handling packaging

Packaging, gaskets and copper packaging should be replaced as directed. After using the adhesive, please assemble the gasket specified in this service manual. When applying adhesive to the gasket, please pay attention to the following:

Thoroughly remove the old adhesive, scratches, dust, paint and grease on the surface of the gasket.

Apply a suitable sealant evenly on both sides of the gasket and wait a few minutes until it is dry. Once the sealant is dry to the touch, it won't stick to your hands, assemble the parts.

Soak the leather packaging in oil before use.

#### **Handle O-ring**

Remember to check the condition of the O-ring. Do not use O-rings that have hardened.

Only use the O-ring specified in the parts list. For example, O-rings used for engine oil are made of special materials, such as silicone rubber, and are resistant to heat and aging. In this case, installing different types of O-rings may cause serious damage to the system and its components.

Lubricate the O-ring to avoid scratching its surface during installation. Silicone rubber O-rings are easily damaged, so be careful not to stretch them excessively.

Deal with the oil seal

Prevent the oil seal from collecting dust, especially dust on the lips, and make sure that there is no hardening or scratching.

Evenly lubricate the lip surface opposite to the oil seal.

Check whether the surface of the shaft where the oil seal is installed is contaminated, rusted or scratched, and then apply grease or lubricant so that the oil seal can be installed easily.

Check the surface of the oil seal lip for scratches. If there are scratches, replace the oil seal.

When inserting the oil seal, use guides and clamps to avoid damage to the oil seal.

After inserting the oil seal, check the inclination (inclination tolerance: 0.2 mm/00 mm, diameter 0.008 inch/3.937 inch).

When applying adhesive to the oil seal, make sure that no adhesive is in contact with the lip surface. Before inserting another seal, completely remove residual adhesive on the rails and clamp

#### Handling the bearings

To assemble the bearing correctly and avoid damage to the bearing, please pay attention to the following:

Thoroughly remove dust and other contaminants that may shorten the life of the bearing. Keep the bearing package until it is installed o

Do not rotate the bearing excessively in order to clean the purifier by blowing in compressed air. Ensure that the oil seal ring is installed in the correct direction.

Please pay attention to the following when installing the bearing:

Neither the outer ring was hit with a hammer to install it, nor the inner ring was hit to insert the outer ring. Hammering like this can cause damage to the bearing track.

When you insert the inner ring of the bearing with a reasonable tolerance, use a clamp and apply pressure to the inner ring. When performing hot insertion with a press-in tolerance, heat the bearing to 120°C (248e F). However, please note that excessive heating will reduce the hardness of the bearing surface.

When you insert a non-split bearing with an inner ring and an outer ring with a reasonable tolerance, use a clamp while pressing the inner ring and the outer ring at the same time.

#### Handling the retaining ring

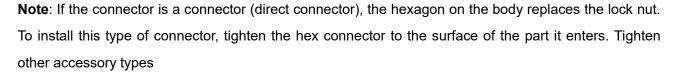
When removing or installing the fixing ring, please use a pair of right ring pliers, being careful not to put too much pressure on the fixing ring.

After installing the fixing ring, check whether the fixing ring is inserted correctly • Assembly of accessories with straight thread and O-ring

seal (suitable for different applications)

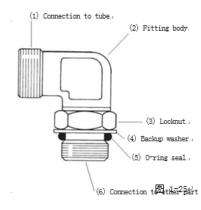
- 1. Seal the lock nut (3), support washer (4) and O-ring Place the piece (5) as far as possible on the main body (2) of the accessory.
- 2. Turn the joint to the part it uses until the support washer (4)Just touched the surface of the part.
- 3. To place the joint assembly in the correct position place the joint body (2)Rotate outward (counterclockwise) up to  $359^{\circ}$
- 4. Tighten the lock nut (3) to the correct diagram of the accessory used The torque shown.
- 5. If the shape of the pipe end of the fitting body is

shown in Figure 1-25 (elbow or Straight body), put the sleeve on the tube before connecting the tube to the end.



High-load (shear casing) pipe fittings: After the pipe passes through the nut and contacts the pipe shoulder in the fitting body, turn the nut with a wrench until you feel a slight decrease in torque.

High-sealing fittings: Place the nut and sleeve on the pipe with the short and heavy end of the sleeve



facing the end of the pipe. Place the end of the pipe against the counter bore in the main body of the fitting and tighten it until the nut is above the last thread on the main body. Just remove the accessory and install it again, and the remaining space will be used.

Flexible fittings: Put the nut and sleeve on the pipe, and push the pipe into the counter bore of the fitting body as much as possible. Tighten the nut until it touches the hexagonal part of the connector body.

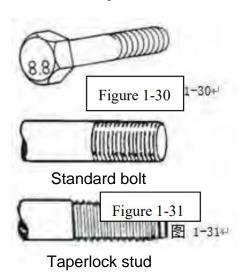
#### 1-9 Standard torque

#### 1-9-1 Standard torque of bolts and nuts

Be careful to avoid mixing metric and imperial size fasteners. Mismatch or incorrect The fasteners may cause vehicle damage or malfunction, or may cause personal injury. If necessary, exceptions to these torques can be given in the service manual.

Before installing any hardware, make sure that the components are in a near new state. Screw. The bolt and nut threads must not be worn or damaged. The hardware must be free of rust and corrosion. Use non-corrosive cleaners to clean the hardware and apply engine oil to the threads and bearings Surface. If you want to use thread glue or other compounds, do not use engine oil. After loosening the fasteners, keep them in good condition and only reuse them under delicate conditions. When replacing a new one, be sure to select fasteners of the same size and grade.

Generally, you can identify it based on the number marked on the head (such as 8.8 or 10.9) The strength of the bolt is shown in Figure 1-30. The following table lists standard bolts and nuts. The standard torque, and the tapered bolt shown in Figure 1-31.



# For metric fasten

| Thread size(mm)   | Metric nuts and bolts |             | Metric taperlock stud |             |
|-------------------|-----------------------|-------------|-----------------------|-------------|
|                   | (M⋅M) ↔               | Pounds/feet | (N·M) ↔               | Pounds/feet |
| M6↔               | 12 ± 3₽               | 9 ± 2≠      | 8 ± 3↔                | 6 ± 2↔      |
| M8+ <sup>3</sup>  | 28 ± 7₽               | 20 ± 5₽     | 17 ± 5↔               | 13 ± 4↔     |
| M10+ <sup>J</sup> | 55 ± 10+ <sup>3</sup> | 40 ± 7₽     | 35 ± 5₽               | 26 ± 4↔     |
| M12↔              | 100 ± 20↔             | 75 ± 15₽    | 65 ± 10↔              | 48 ± 7↔     |
| M14+              | 160 ± 30↔             | 120 ± 22₽   | -41                   |             |
| M16+ <sup>3</sup> | 240 ± 40↔             | 175 ± 30↔   | 110 ± 20↔             | 80 ± 15↔    |
| M20↔              | 460 ± 60↔             | 340 ± 44↔   | 170 ± 30↔             | 125 ± 22+   |
| M24↔              | 800 ± 100+            | 600 ± 75+   | 400 ± 60↔             | 300 ± 45↔   |
| M30+              | 1600 ± 200₽           | 1200 ± 150↔ | 650 ± 80€             | 480 ± 60+   |
| M36+              | 2700 ± 300₽           | 2000 ± 225₽ | 870 ± 100↔            | 640 ± 75+   |

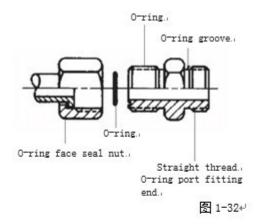
# For British fasteners

| Tt                | British nuts and bolts |                       | British taperlock stud |           |
|-------------------|------------------------|-----------------------|------------------------|-----------|
| Thread size(inch) | (M·M) ↔                | Pounds/feet           | (N⋅M) ↔                |           |
| 1444              | 12 ± 3+1               | 9 ± 2+                | 8 ± 3+1                | 6 ± 2+    |
| 54164             | 25 ± 6↔                | 18.0 ± 4.5↔           | 17 ± 5↔                | 13 ± 4↔   |
| 348+1             | 47 ± 9↔                | 35 ± 7+               | 35 ± 5↔                | 26 ± 4+1  |
| 7∲16↔             | 70 ± 15↔               | 50 ± 11+ <sup>1</sup> | 45 ± 10↔               | 33 ± 7↔   |
| 1≠2+              | 105 ± 20+              | 75 ± 15↔              | 65 ± 10↔               | 48 ± 7+/  |
| 9∳16↔             | 160 ± 30↔              | 120 ± 20↔             | -47                    | -4        |
| 5#8₩              | 215 ± 40+1             | 160 ± 30↔             | 110 ± 20↔              | 80 ± 15↔  |
| 3444              | 370 ± 50↔              | 275 ± 35↔             | 170 ± 30↔              | 125 ± 22+ |
| 7484              | 620 ± 80+              | 460 ± 60↔             | 260 ± 40↔              | 190 ± 30+ |
| 1+1               | 900 ± 100+             | 660 ± 75€             | 400 ± 60↔              | 300 ± 45+ |
| 1+1 / 8+          | 1300 ± 150↔            | 950 ± 100↔            | 500 ± 70↔              | 370 ± 50+ |
| 1+1 / 4+1         | 1800 ± 200↔            | 1325 ± 150↔           | 650 ± 80₽              | 480 ± 60+ |
| 1+3 / 8+          | 2400 ± 300↔            | 1800 ± 225↔           | 750 ± 90↔              | 550 ± 65+ |
| 1+1 / 2+          | 3100 ± 350↔            | 2300 ± 250↔           | 870 ± 100₽             | 640 ± 75+ |

#### 1-9-2 Standard torque for fastening accessories

# Standard torques for O-ring surface seal fittings

|                   | Accessories for straight thread o-ring |           |  |  |
|-------------------|--|-----------|--|--|
| Thread size(inch) | (N·M) ← Pounds/fee                     |           |  |  |
| 5⊬ 16-24⊬         | 5.0±1.5↔                               | 45 ± 15↔  |  |  |
| 3⊬⁄ 8−24⊬         | 12 ± 2↔                                | 110 ± 20↔ |  |  |
| 2∲7 - 16 ↔        | 20 ± 4↔                                | 15 ± 3↔   |  |  |
| 1⊬/ 2-20⊬         | 40 ± 5↔                                | 30 ± 4↔   |  |  |
| 9⊬/ 16-18⊬        | 40 ± 5↔                                | 30 ± 4↔   |  |  |
| 3⊬/ 4-16⊬         | 100 ± 15↔                              | 75 ± 10↔  |  |  |
| 7⊬/ 8-14⊬         | 135 ± 15↔                              | 100 ± 10↔ |  |  |
| 1∉1 / 16-12∉      | 200 ± 25↔                              | 150 ± 20√ |  |  |
| 1+3 / 16-12↔      | 250 ± 25↔                              | 185 ± 20↔ |  |  |
| 145 / 16-124      | 300 ± 40↔                              | 225 ± 30₽ |  |  |
| 145 / 8−124       | 300 ± 40↓                              | 225 ± 30₽ |  |  |
| 1+₹ / 8-12+       | 300 ± 40√                              | 225 ± 30↔ |  |  |
| 241 / 2-124       | 300 ± 40↔                              | 225 ± 30↔ |  |  |



| Th d .:(:t.)      | Sealing joint nuts for O-ring face |             |  |
|-------------------|------------------------------------|-------------|--|
| Thread size(inch) | (M·M) ↔                            | Pounds/feet |  |
| 9+/ 16−18+/       | 16 ± 3↔                            | 12 ± 2↔     |  |
| 14 / 16−16↔       | 30 ± 4↔                            | 22 ± 3↔     |  |
| 1∌ / 16-16↔       | 50 ± 7↔                            | 37 ± 5↔     |  |
| 1+14+             | 90 ± 10↔                           | 65 ± 7↔     |  |
| 1+8 / 16−12+      | 120 ± 15↔                          | 90 ± 10↔    |  |
| 1+₹ / 16-12+      | 160 ± 20₽                          | 120 ± 15↔   |  |
| 1411 / 16-124     | 190 ± 20√                          | 140 ± 15↔   |  |
| 2-124             | 215 ± 25↔                          | 160 ± 20↔   |  |

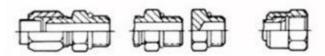
#### Hose clamp - belt type

| Clamp width | New hose torque | Torque for re-tightening |
|-------------|-----------------|--------------------------|
| 7+9 mm .    | 0+9±0.2 N·m+    | 0.7±0.2 N·m (6+/         |
| (0.312 in   | (8±2 lb·in)+    | ±2 lb·in) +/             |
| 10.5 mm +   | 4+5±0.5 N·m+    | 3.0±0.5 N·m (25+/        |
| (0.531 in   | (40±5 lb·in)+   | ±5 lb·in)+/              |
| 18.9 mm     | 7+5±0.5 N·m+    | 4.5±0.5 N·m (40↔         |
| (0.625 in   | (65±5 lb·in)+   | ±5 lb·in) ↔              |



图 1-33↔

# 37° bell and straight threaded O - ring accessories



Pic 1-34

图 1-2/4

37℃ bell and straight threaded O - ring accessories (Sealing accessories for O - ring surface are excluded)

| Nominal pipe external diameter |          | Thread diameter (in) | Standard torque        |            |
|--------------------------------|----------|----------------------|------------------------|------------|
| Metric                         | Inch     | Inch                 | (N·M)                  | Ponds/Feet |
| 3+18+                          | 0.125+   | 5/16+                | 5.0±1.5↔               | 4 ± 1+1    |
| 4+76↔                          | 0.188↔   | 3/84                 | 11.0 ± 1.5↔            | 8 ± 1+     |
| 6+35+                          | 0. 250+1 | 7/16↔                | 16 ± 2↔                | 12 ± 1↔    |
| 7+94+                          | 0.312+   | 1/2₽                 | 20 ± 5€                | 15 ± 4+    |
| 9+52+                          | 0.375+   | 9/16₽                | 25 ± 5↔                | 18 ± 4↔    |
| 9+52+                          | 0.375+   | 5/84                 | 35 ± 5₽                | 26 ± 4+    |
| 12.70↔                         | 0.500↔   | 3/4+                 | 50 ± 7↔                | 37 ± 5↔    |
| 15.88↔                         | 0. 625↔  | 7/84                 | 65 ± 7↔                | 48 ± 5↔    |
| 19.05↔                         | 0, 750↔  | 1-1 / 16+            | 100 ± 10+ <sup>1</sup> | 75 ± 7₽    |
| 22.22↔                         | 0.875+   | 1-3 / 16+            | 120 ± 10↔              | 90 ± 7+    |
| 25. 40+                        | 1. 000+  | 1-5 / 16+            | 135 ± 15↔              | 100 ± 11+  |
| 31.75↔                         | 1. 250↔  | 1-5 / 8+             | 180 ± 15+              | 135 ± 11+  |
| 38.10↔                         | 1. 500↔  | 1-7 / 8↔             | 225 ± 15+              | 165 ± 11₽  |
| 50.80↔                         | 2.000↔   | 2-1 / 2+             | 320 ± 30+              | 240 ± 22+  |

#### 45° bell shape and 45° inverted bell fittings





| 1-35↩

| Nominal pipe external diameter |         | Thread diameter (in) | Standard torque |            |
|--------------------------------|---------|----------------------|-----------------|------------|
| Metric                         | Inch    | Inch                 | (N·M) ↔         | Ponds/Feet |
| 3⊬18⊬                          | 0. 125↔ | 5/16↩                | 5.0±1.5↔        | 4 ± 1↔     |
| 4+76+ <sup>1</sup>             | 0.188↩  | 3/8₽                 | 8.0±1.5↔        | 6 ± 1 ↔    |
| 6+35↔                          | 0. 250↔ | 7/16↩                | 11 ± 2↔         | 8 ± 1 ↔    |
| 7+94↔                          | 0.312↔  | 1/2↔                 | 17 ± 3₽         | 13 ± 2↔    |
| 9+52+                          | 0.375↔  | 5/8₽                 | 30 ± 3↔         | 22 ± 4↔    |
| 11. 11₽                        | 0. 438↔ | 11/16↔               | 30 ± 3↔         | 22 ± 2↔    |
| 12.70↔                         | 0.500↔  | 3/4₽                 | 38 ± 4↔         | 28 ± 3↔    |
| 15.88↩                         | 0.625↔  | 7/8↔                 | 50 ± 5↔         | 37 ± 4↔    |
| 19.05↔                         | 0.750↔  | 1-1 / 16+/           | 90 ± 8↩         | 65 ± 6↔    |
| 22. 22↔                        | 0.875↔  | 1-1 / 4↔             | 100 ± 10↔       | 75 ± 7₽    |

# Thread fittings for air conditioning and conical pipes

| Thread fittings for conical pipes |                              |            |                         |           |
|-----------------------------------|------------------------------|------------|-------------------------|-----------|
| Thread diameter (in.)             | Threads with le2200e sealant |            | Threads without sealant |           |
|                                   | (M·W) ↔                      | Ponds/Feet | (N·M) +                 | Ponds/Fee |
| 14/ 16-274                        | 15↔                          | 11€        | 20↔                     | 15↔       |
| 1+/ 8-27+/                        | 20↔                          | 15↔        | 25↔                     | 18↩       |
| 1/8-14↔                           | 25↔                          | 18↩        | 35₽                     | 26↔       |
| 34∕ 8-184                         | 35↩                          | 26↩        | 45↔                     | 33↔       |
| 1+/ 2-14+/                        | 45↔                          | 33↔        | 604                     | 45↔       |
| 3+√ 4-14+                         | 60↔                          | 45↔        | 75₽                     | 55↔       |
| 1+11 1/2↓                         | 75↩                          | 55↔        | 90₽                     | 65↔       |
| 1+1 / 4-11 1/2↓                   | 95↔                          | 70↔        | 110↩                    | 80₽       |
| 1+1 / 2-11 1/2↔                   | 110↔                         | 80↔        | 130↔                    | 95↔       |
| 2+11 1/2↓                         | 130√                         | 954-       | 160↔                    | 120↔      |

#### 2 Electronic System

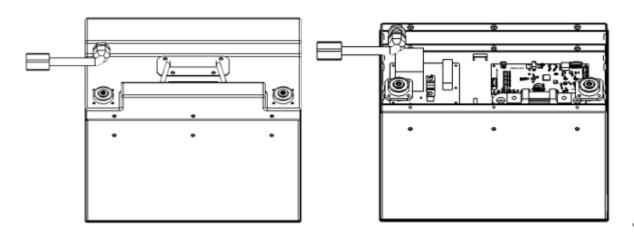
#### 2-1 Overview

This model is equipped with an electrical system with the following components:

- 1. The battery supplies the power to the electrical system [Section 2-2]
- 2. The emergency switches may be pressed in emergency to turn off all DC and AC circuits [Section 2-3]
- 3.Motors, controllers, and associated equipment are providing the necessary drive and pump power to the vehicle based on their interactions with sensors, switches, relays, actuators, as well as various parameter settings. [Section 2-4]
- 4. When the load is supplied at a current above the limit, the fuse will protect all DC loads from over-current by cutting off the load's power supply. [Section 2-5-1]
- 5.Other DC loads that activated by the operator's direct requirements will work independently of the controller. First, such DC loads not regulated by controllers and are not the purpose of controllers' signals. However, they may interact with controllers in some configuration. Such loads include light sets and horns. [Section 2-5-3 to 2-5-5]
- 6. The display board monitors the vehicle, informs the user of its condition and provides basic functions for mode setting, diagnosis and calibration [Sections 2-6]
- 7. The handheld console provides the same functions as the instrument board, but more detailed [sections 2-7]

#### 2-2 Battery (Lead-acid)

#### 2-2-1 Appearance and Specifications



2-1

| Item             |                          | Parameters                | Remark                  |
|------------------|--------------------------|---------------------------|-------------------------|
| Specifications   |                          | 24V60Ah                   | 8-LFP-60-EV-NOB         |
| Nominal voltage  |                          | 25.6V                     |                         |
| Rated Capacity   |                          | 60Ah                      | 0.5C Discharge          |
| reference weig   | ght                      | approximately             |                         |
|                  |                          | 16.5kg                    |                         |
| Discharge        | Maximum continuous       | 100A                      |                         |
| C                | discharge current        |                           |                         |
|                  | Maximum pulse            | 150A                      | No more than 10 seconds |
|                  | discharge current        |                           |                         |
|                  | Discharge cut-off        | ≥22V                      |                         |
|                  | voltage                  |                           |                         |
| Discharge        | Standard charging        | 20A                       |                         |
| _                | current                  |                           |                         |
|                  | Maximum charging         | 30A                       |                         |
|                  | current                  |                           |                         |
|                  | Charging voltage         | 28~28.8V                  |                         |
| Internal resista | ance                     | Less than 20mQ            | Between the             |
|                  |                          |                           |                         |
|                  |                          |                           | positive and            |
|                  |                          |                           | negative poles          |
| Charging tem     |                          | 5~45°C                    |                         |
| Discharge ten    | nperature                | -20∼60°C                  |                         |
| Storage temper   | erature range            | -20∼50°C                  |                         |
| BMS              | Overcharge protection    | Single section 3.9V±0.03V |                         |
| parameter        | voltage                  |                           |                         |
|                  | Over discharge           | Single section 2.5V±0. 3V |                         |
|                  | protection voltage       |                           |                         |
|                  | Overcurrent protection   | 120A                      |                         |
|                  | current                  |                           |                         |
|                  | Short circuit protection | 200A                      | Fuse 200A               |
|                  | current                  |                           |                         |
|                  | Charge control           | CAN bus control           |                         |

# 2-2-2 Analysis and explanation of lithium battery fault

| Battery p | ack system faul   | t repair table   |  |   |   |
|-----------|---|--|--|---|---|
| Number    | fault types   | Preliminary judgment   | Failure to confirm   | Failure to confirm  | The measures  |
| 1         | No output<br>after the<br>battery pack<br>is started<br>and the<br>switch<br>indicator is<br>on | 1.Abnormal Communication with the vehicle; 2.Internal components of the system are damaged | 1.check the monitor screen of a vehicle alarm code, and confirm the specific fault, if confirmed as the CAN communication, disconnect the discharge connectors, measurement on both ends of the battery pack discharge connectors CAN communication if there are 120 Q resistance; | 1.When the resistance is infinite, it indicates that CAN communication wiring harness is disconnected. Firstly, measure whether CAN Hand CAN L are on normally between discharge connector and panel communication port, and then measure whether CAN of panel communication wiring harness is on; 2.there is resistance, but is far larger than 120 0, damage may be inside the BMS CAN chip If there is | 1.Replace the damaged wiring harness; 2.Replace the battery |
| 1         |   |  | the  | output,   | locomotive  |

|                              |   |  | discharge plug,<br>start the<br>battery pack<br>separately,<br>and check<br>whether the<br>discharge plug<br>has output;  | there may be an error in the locomotive internal circuit, resulting in the battery pack unable to output | communication<br>and power<br>lines |
|------------------------------|---|--|---|--|-------------------------------------|
| 2                            | No output<br>after the<br>battery pack<br>is started,<br>the switch | 1. Internal components of the system are damaged; 2.The system                             | 1.Select the DC voltage range of the multi meter, measure the total positive and negative voltages at both ends with a stylus, and check whether the total voltage of the system is normal; | The system voltage is low and BMS cannot work normally   | Charge the battery pack first       |
| indicator<br>light is not or | indicator<br>light is not on  | voltage is insufficient  | 2.Use the multi meter conducting file to measure whether the two wiring harnesses of the panel communication wire harness are normal conducting   | Wire harness failed when both ends of wire harness failed to conduct properly                            | Replace the battery                 |
| 3                            | The battery pack cannot be charged. The switch indicator is on      | 1.Abnormal communication with the vehicle; 2.Internal components of the system are damaged | 1.Measure whether the wiring harness of charging socket 12V, GND, CANH and CNAL is in normal conduction   | The conduction is not normal   | Check the charging harness          |

|  |             |   | 2/connect the    |                       |  |
|--|-------------|---|------------------|-----------------------|--|
|  |             |   | charger, to      |                       |  |
|  |             |   | check the        |                       |  |
|  |             |   | charger shows    |                       |  |
|  |             |   | fault code, off  |                       |  |
|  |             |   | to see if        |                       |  |
|  |             |   | there's any      | Did not               |  |
|  |             |   | loose for        | measure to            |  |
|  |             |   | charging port    | 120 Q                 | Replace the                                |
|  |             |   | terminals,       | resistance,           | battery                                    |
|  |             |   | terminal, back   | CAN damage            |  |
|  |             |   | measurement      | the chip              |  |
|  |             |   | CAN              |                       |  |
|  |             |   | communication    |                       |  |
|  |             |   | if there         |                       |  |
|  |             |   | are 120 Q        |                       |  |
|  |             |   | resistance on    |                       |  |
|  |             |   | both ends        |                       |  |
|  |             |   | 1.Disconnect     |                       |  |
|  |             |   | the charger      |                       |  |
|  |             |   | from the battery |                       |  |
|  |             |   | pack and         | The charger           |  |
|  |             |   | separately       | has no                |  |
|  |             | he battery has no 12V ack won't auxiliary power harge and output; | measure          | 12V auxiliary Replace | Replace the                                |
|  |             |   | whether there    |                       | charger                                    |
| The battery pack won't charge and the switch | The battery |   | is 12V auxiliary |                       |  |
|  | pack won't  |   | power output     |                       |  |
|  | charge and  |   | after the        |                       |  |
|  | the switch  |   | charger is       |                       |  |
|  | indicator   | components of   | started up;      |                       |  |
|  | isn't on    | the system are  | 2.Measure        |                       |  |
|  |             | damaged   | whether the      | vvire harness         | Replace the charging socket wiring harness |
|  |             |   | wiring harness   |                       |  |
|  |             |   | of charging      |                       |  |
|  |             |   | socket 12V and   |                       |  |
|  |             |   | GND is in        | Proporty              |  |
|  |             |   | normal           |                       |  |
|  |             |   | conduction       |                       |  |

## 2-2-3 Precautions (Lithium battery)

#### a). Charging requirements:

The battery has a built-in protection system, when the system is over-discharged, the internal MOS will cut off the output, showing a high resistance state (OD), then the charger needs to charge to activate. The maximum charging voltage of the charger is limited to 28.8V, two-stage constant voltage charging, charging cut-off current 0.3~0.5A.

#### b). Cautions:

- 1) The battery is not allowed to be charged below 0°C, otherwise it will seriously cause battery performance degradation and even safety incidents.
- 2) The battery is not allowed to be charged at low temperature, and should not be used at low temperature (cold storage or outdoor in winter), especially in places where the ambient temperature changes drastically, the battery will produce condensation water droplets inside the battery, the water droplets will break the battery internal electronic devices, resulting in unpredictable hidden problems. After taking out from the cold environment, the battery should be placed at room temperature for at least 4 hours before use.
- 3) The battery protection level is IP54, you can't use water to rinse the battery directly, you can use a cloth dipped in water to wipe, but not dipped in water to wipe the charge and discharge port.
- 4) The battery should not be used in the marine salt spray environment, nor in the humid environment for a long time (aquatic market, cold storage, ice factory, bathroom, acid factory, etc.).
- 5) When the lithium battery pack is not used for a long time, please do not store it in a fully charged state, try to store it in a semi-charged state (the battery voltage is around 26V) and store it in a cool place.

## 2-2-4 Removal and installation of lithium battery

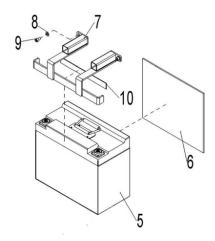
## **Preliminary steps**

- 1 Park the vehicle safely and remove the cover.
- 2 Turn off the key switch

## **Program**

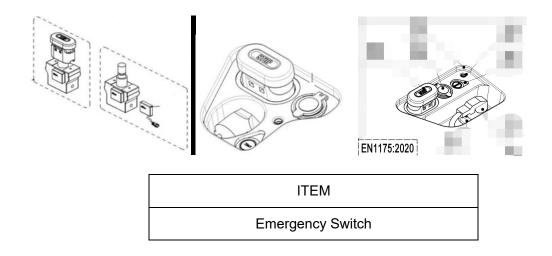
- 1 Remove screw (9) and remove battery mounting plate (7)
- 2 Disconnect the battery control cable
- 3 Remove the positive and negative screws of the battery and remove the battery power cord®
- 4 Remove the battery®

Follow the steps above to install the battery in reverse order



## 2-3 Emergency switch

## 2-3-1 Appearance and Specifications



## 2-3-2 function

The emergency stop switch is used to stop the operation of the vehicle by cutting off the current in the electrical system in an emergency. When pressed, all DC and AC circuits are open o

### The DC circuit is open

Once the emergency stop switch is turned on, the battery's positive terminal and the key switch are disconnected, thereby cutting off power to all loads supplied by the key switch. As a result, all DC loads will be cut off.

### **Detection**

state)

### A) Mechanical properties

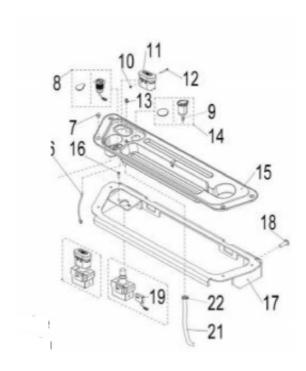
Press the red button down with the palm of your hand. The palm can obviously feel a reliable pause point locked. When pulling up, there is also a reliable sense of suction.

### B) Electrical properties

Put the digital multi meter in on-off gear, and connect the two meter pens on the metal terminals on both sides of the emergency stop switch. When the emergency stop switch is not pressed down, the multi meter buzzer will call (that is, it is in the on-off state). When the emergency stop switch is pressed down, the multi meter buzzer does not ring (that is, it is in the disconnected

Connect the two meter pens to the two metal terminals of the micro switch on the emergency stop switch. When the emergency stop switch is not pressed down, the multi meter buzzer will be called (that is, it is in the on state). When the emergency stop switch is pressed down and locked, the multi meter buzzer does not ring (that is, the switch is in the disconnected state)

Connect the two meter pens to the two metal terminals of the micro switch on the emergency stop switch. When the emergency stop switch is not pressed down, the multi meter buzzer will be called (that is, it is in the on state). When the emergency stop switch is pressed down and locked, the multi meter buzzer does not ring (that is, the switch is in the disconnected state)



#### Removal and installation

### Preliminary steps

- 1 Park the vehicle safely and remove the cover.
- 2 Turn off the key switch.
- 3 Disconnect the battery connector Program
- 1.Disconnect the button switch (8) and the USB power cable.
- 2 Remove the emergency stop switch cap screw (12) and remove the emergency stop switch cap (11) •
- 3 Remove instrument panel screw (7) and remove instrument panel (15) •
- 4 Remove the power cord on both sides of the emergency stop switch o
- 5 Disconnect the connection line for the micro switch (19)
- 6 Remove the fixing screw (16) of the emergency stop switch to remove the Perform the above steps in reverse order to install the emergency stop switch

# 2-4 Controller and associated equipment

## 2-4-1 appearance

## a.Controller Curtis 1212C



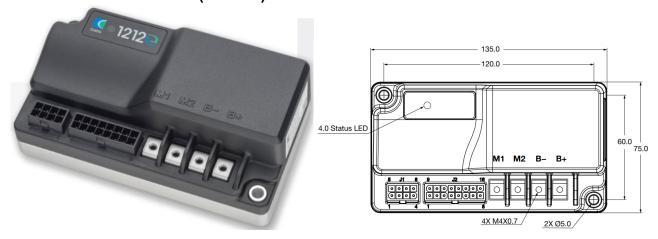
Logical part plug-in: 14 core Molex Mini-Fit Jr.,P/N 39-01-2140

Electromagnetic brake plug: 2 core Molex Mini-Fit Jr., P/N 39-01-2020;

Handheld programming port plug-in 4 core Molex Mini-Fit Jr., P/N 39-01-2040;

Power part plug-in : AMP The plug-in, P/N 12076SL02

## b. Curtis controller 1212e(EN1175)



Docking connectors: 8 core Molex Mini-Fit Jr. 16 core Molex Mini-Fit Jr.

### 2-4-2 Features

The controller is connected through the following sensors, switches, relays and actuators.

Key switch

switch

accelerator

Handle proximity switch

Emergency reverse switch

Hydraulic control switch

These devices provide DC power and interact with the controller. The controller activates or receives data from them based on many parameter settings to control the motor.

By correctly setting the various motor technical parameters and control technical parameters and function values of the controller, the safe and efficient work performance and complete operating functions of electric vehicles can be realized o

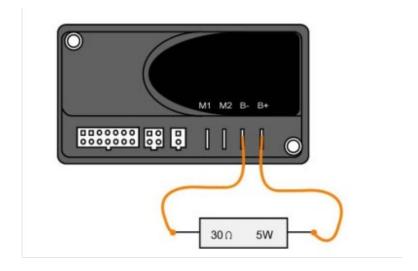
- I. The crawling speed of electric vehicles can be adjusted. Through the crawl speed setting function of the controller, the electric vehicle can run for a long time at low speed °
- 2 > The acceleration rate can be adjusted. The acceleration rate is the "soft and hard" feeling of the accelerator pedal when operating an electric vehicle. By setting the acceleration rate, the vehicle can meet the requirements of acceleration operation under different working conditions..
  - 3-The maximum travel speed can be adjusted. Reasonable setting of the maximum travel speed of electric vehicles can prevent the traction motor from overloading due to excessive vehicle speed.
- 4. Safety protection function. If the power element of the controller is damaged during the operation of the vehicle, the controller will disconnect the main contactor in the shortest time; when the controller temperature rises too high, the controller will automatically limit the armature current of the motor; when the battery voltage is too high When low, the controller will stop working to ensure safety.
- 5. The motor controller has a self-diagnosis function. During the working process of the controller, once a fault occurs, the fault code will be displayed on the handle display instrument, and the controller will automatically stop working to ensure the safety of the operating system o
  - 6. The handle display meter will display the battery power and accumulated working hours.

### 2-4-3 test

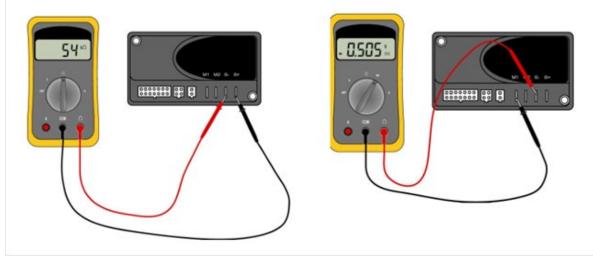
#### A. Controller

Measure the diode voltage of the AC MOSFET circuit inside the controller to check whether it is burned or damaged.

Remove the cables and wiring harness connected to the controller, and completely discharge the internal capacitor power (discharge the B+ and B-terminals with a resistance of 30Q/5W).



Use a multi meter to measure according to the table below and check whether it is normal. Each test item must be tested repeatedly for more than 3 times



| ITEM | Multi meter terminal |            | Normal range  |             |
|------|----------------------|------------|---------------|-------------|
|      | Red test lead        | Black test | Polar value   | Resistance  |
|      |                      | lead       | determination | measurement |
| 1    | B+                   | B-         |               | 40ΚΩ+       |
| 2    | B+                   | M2         |               | 80ΚΩ+       |
| 3    | B+                   | M1         |               | 80ΚΩ+       |
| 4    | M1                   | M2         |               | 60ΚΩ+       |
| 5    | B-                   | M2         | 0.3-0.6V      |             |
| 6    | B-                   | M1         | 0.3-0.6V      |             |

Pull the multi meter to the Q position (determination of resistance value) Pull the multi meter to the diode position (determination of polarity value)

#### 2-4-4 Removal and installation

#### **Access control panel**

- 1 Lower casing to enter drive motor controller.
- 2 Close the key switch and emergency stop switch.
- 3 Disconnect the battery.
- 4 Leave the key switch on to make the power module discharge. Two 30 seconds •
- 5 Turn off key switch.

**Note:** Remember that the controller contains AN ESD (electrostatic discharge) sensitive component. Appropriate precautions should betaken when connecting, disconnecting and handlingo Drive motor controller removed/installed

Note: Remember that the controller contains AN ESD (electrostatic discharge) sensitive component.

Appropriate precautions should be taken when connecting, disconnecting and handling

- 1. Disconnect the control harness from the connector port of the controller.
- 2. Disconnect the B+,B-,M1 and M2 cables.
- 3. Release and remove the controller.
- 4. .Perform the above steps in reverse order to install the drive motor controller

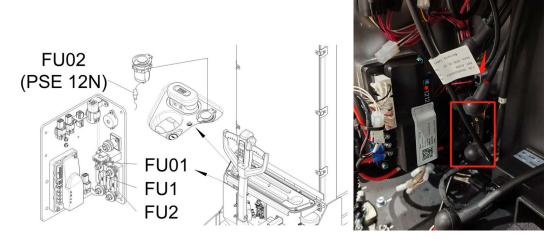
### 2-5 Miscellaneous load

#### 2-5-1 fuse

### A. Function and composition

<u>To protect dc loads from over current, fu</u>ses are equipped with the following specifications:

| Item | Specifications |
|------|----------------|
| FU1  | 60A            |
| FU2  | 150A           |
| FU01 | 10A            |
| FU02 | 1.5A           |



- B. Remove and install Preliminary steps
- 1.Remove the shell to get inside the vehicle
- 2. Close the key switch and emergency stop switch.
- 3. Disconnect the battery connector,

#### procedure

- 1 Open the fuse cover to take out the fuse (FU01).
- 2 Remove bolts and washers, then remove fuses (FU1 and FU2)
- 3. Unscrew the fuse box to take out the fuse (FU02)
- 4.Do the above steps in reverse order to install the fuse box.

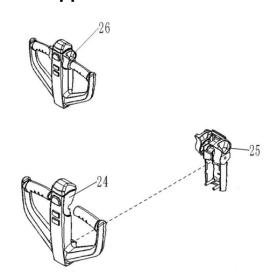
Note: When replacing a fuse, a new fuse of the same type and specification must be used to prevent electrical damage. If fuses are blown frequently, there may be an electrical fault.

#### 2-5-2 horn

The speaker is directly powered by a battery. It is used to sound an alarm to warn people nearby

### 2-6 Tiller

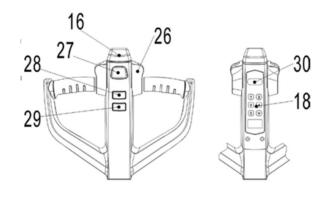
## 2-6-1 appearance



## 2-6-2 functions

Tiller head through the up and down buttons, belly switch, tortoise speed button,

Accelerators and password locks engage with controllers to control some of the vehicle's movements



A Password Lock (18)

B up and down (28,29)

C Belly switch (16)

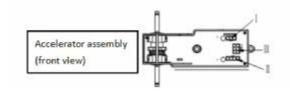
D Accelerator (26)

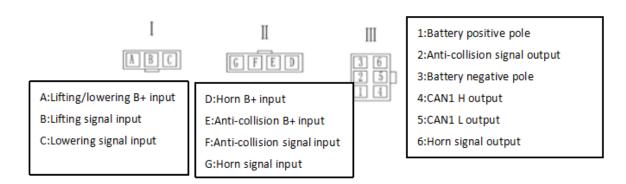
E Turtle Speed Switch (30)

F Horn switch (27)

### 2-6-3 Tiller head detection

1) Use a multi meter to measure the resistance between pin 4 and pin 5 of III. Rated resistance: 120.0





2) Use a multi meter to measure the on/off condition of the belly switch and the horn switch respectively. If not connected and CAN resistance is wrong, replace tiller

### 2-6-4 Removal and installation

Preliminary steps

1 Remove the shell to access the vehicle interior

2Turn off the key switch and emergency stop switch, program

- 1. Remove the fixing screw of the lower cover of the tiller and disconnect the cable to remove the lower cover of the tiller (25)
- 2 Remove the tiller upper cover fixing screw to remove the tiller upper cover (24)

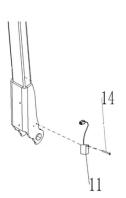
Perform the above steps in reverse order to install the tiller head assembly (26).

## 2-6-5 tiller proximity switch removed and installed

Preliminary steps

- 1 Safe parking o
- 2 Close the key switch and emergency stop switch program
- 1. Press down the tiller to disconnect the harness of the proximity switch •
- 2 Remove the retaining screw (14) of the proximity switch and remove the proximity switch.

Follow the steps above in reverse order to install the tiller proximity switch (11).



# 2-6-6 Tiller air spring removed and installed

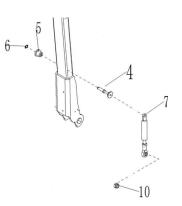
Preliminary steps

- 1 Safe parking
- 2 Close the key switch and emergency stop switch

Program

- 1 Press down the tiller to disconnect the proximity switch from the tiller
- 2 Remove the fixing screw at the lower end of the air spring (10).
- 3 Remove the fixed shaft retainer (6) and the fixed shaft (4) to remove the air spring (7).

Install the tiller air spring in reverse order.



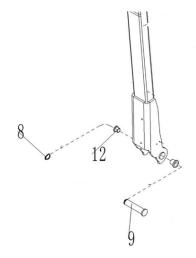
### 2-6-7 Tiller removed and installed

Preliminary steps

- 1 Safe parking.
- 2 Close the key switch and emergency stop switch.

Program

- 1 Press down the tiller to disconnect the proximity switch from the tiller harness.
- 2.Remove the fixing screw (10) at the lower end of the air spring.
- 3.Remove pin retainer (8) and pin shaft (9) to remove tiller Follow the steps above to install tiller s in reverse order



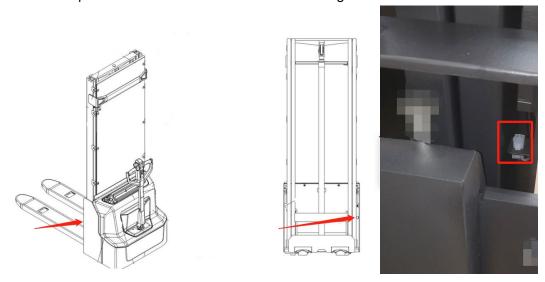
### 2-7 CURTIS Handheld programmer

### 2-7-1 Operation precautions and connection to the vehicle controller:

The attention function of the handheld unit is to facilitate vehicle inspection and maintenance. It is not allowed to adjust the controller parameters without the approval of the vehicle manufacturer to avoid vehicle and personal safety accidents.

After the handheld unit modifies the parameters, it will be automatically saved, just turn off the key switch and restart it.

The CURTIS handheld unit can be connected when the controller is powered on or off. The connection port of the handheld unit is shown in the figure below:



## 2-7-2 Vehicle fault reading process

After connecting the handheld unit to the controller, turn on the key switch

According to the CURTIS handheld unit menu list, find: Faults.

When running the vehicle, the English fault content will appear when the cursor is flashing, please refer to the fault code table for interpretation

## 2-7-3 Vehicle signal detection

After connecting the handheld unit to the controller, turn on the key switch

According to the menu list of the CURTIS handheld unit, find: Monitor...

If necessary, open the corresponding sub-item of the detection menu, run the vehicle, and observe the change of the handheld value.

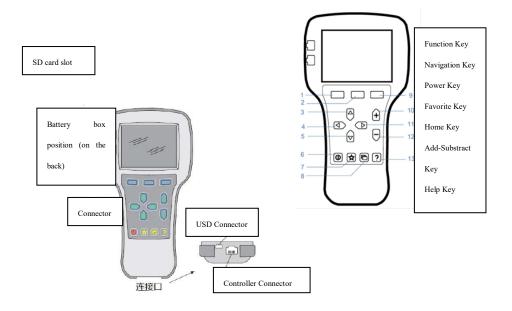
#### 2-7-4 CURTIS Handheld unit menu content

Curtis 1313 handheld programmer is used to configure the Curtis electronic control system. Through this programmer, you can adjust and save the set parameters, real-time monitoring of controller data and fault diagnosis

Warning: The control system will affect the acceleration rate, deceleration rate, hydraulic system and brakes of the vehicle. If the vehicle control system is programmed incorrectly or exceeds safety, a dangerous situation will occur. Only the vehicle manufacturer or an authorized service agent can program the control system



The programmer has 2 interfaces, one is used to communicate with the electronic control, the other is used to communicate with the PC, the programmer has a battery box and a memory card slot

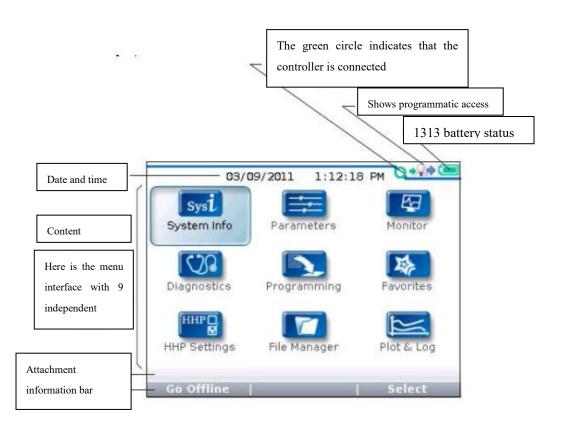


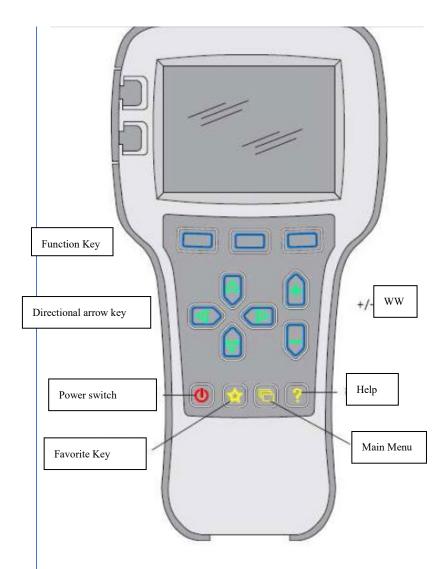
#### 1 Power on the programmer

Insert the cable of the handheld programmer into the programming port of the controller to connect to the controller. After connecting to the controller, the handheld programmer will automatically power on and display the control information on the programmer.



When the programmer finishes the loading of the controller information, the main menu will displayed





#### function keys

The three keys will be blank because the function of the three keys is based on the specified content. At any given time, the functions of the buttons are displayed on the LCD screen above.

#### Directional arrow key

The information displayed can be selected by pressing up, down, or left or right through 4 directional keys.

#### + /-Button

The parameters can be added or subtracted by the two keys. Meanwhile, "+" refers to "Yes" in the operation system, and "-" refers to "No", which may be used as a scrolling options in some cases Power switch

When the programmer inserts an already powered controller, it is not necessary for the programmer to be initiated by pressing the power switches, and the programmer will start up automatically. When it is held down for a few seconds, the programmer will prompt turn off confirmation, which shall be answered by selecting "Yes" or "No" of the function keys. When the programmer is turned off, a few seconds of pressing will trigger the restarting of the programmer.

#### Key of favorite

There are 2 ways to enter the menu of "Favorites" 1. You can enter through the main menu "Favorites"; 2. You can also press this key to enter

#### 2. Menu structure

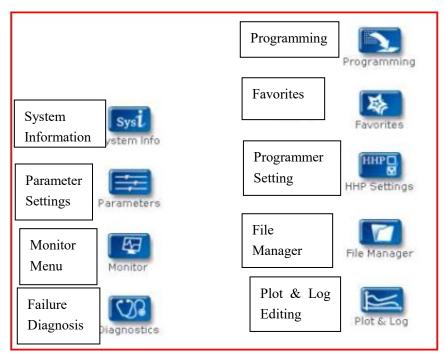
The main menu consists of nine submenus, each of which is displayed with a specific icon, and each item of the submenu is arranged in a hierarchy.

Some menus contain one item only, but most menus contain more than one item, and you can access the next level of submenus through each folders. It is possible for you to expand the table through grid options, enter a set of execution commands through dialog options, and return to the next level of menu whichever interface you are in.

All nine submenu names are shown in bold on the main menu and below the icons. When you enter the stepped menu, the name of the submenu or the path you are in are displayed at the top of the screen.



#### Nine main menus



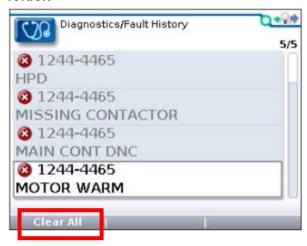
#### 3 Fault diagnosis menu

In the main menu, Select the "Diagnostics" Fault diagnosis icon and press the corresponding function key to enter the Fault diagnosis menu, which includes two folders: "Present Errors" and "Fault History".

Note: the fault caused by a temporary event captured in the circuit is not a real system fault in some cases. And you can determine if the fault really exists by restarting the system and observing the automatic fault indication.

In the history failure folder, the failures listed are all failures encountered after the last history failure was cleared, which can be restarted by clearing the fault content in the entire

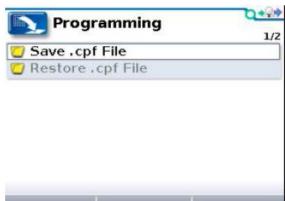
#### folder.



"Clear All" is used to Clear the history failure folders. A function key will be highlighted separately if there is a history failure in the history failure folder, and will be grayed out if there is no history failure.

### 4. Programming edit menu

Select the Programming icon in the main menu, and press the function key corresponding to "Select" to enter the menu. Menus may be programmed to store and restore the setting files of parameter (.cpf files)



#### Save.cpf Files

The Save. CPF File function in the program menu may be used to backup current setted parameters. You can save as many.cpf files as you want, and each.cpf file shall be named differently.

#### Restore.cpf Files

CPF Files to restored may be selected from the earlier saved. CPF Files instead of the current controller's. CPF Files. When the entire data recovery process is completed,

### 5. Parameter Settings

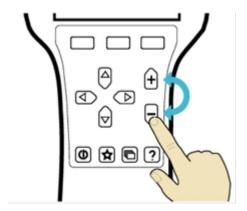
Select "Parameters" from the main page and press "Select" to enter the parameter setting page, in which you can adjust or modify the parameters of the controller.





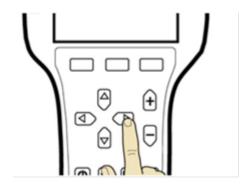
Parameters can be adjusted or modified in two ways: one is in the parameter list page as shown in the figure below;



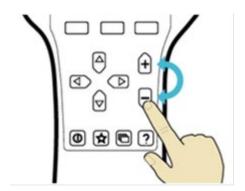


### The other is through the parameter edit page as shown below









# 2-8 Troubleshooting for each fault code

## Fault code measures

| Cod<br>e | Display              | Cause  | Source     |
|----------|----------------------|--|------------|
| 0        | LOW_BDI              | Low battery  | 1212C-2503 |
|          | LOVV_BDI             | Low battery  | controller |
| 1        | PUMP_SRO_FAULT       | The lifting or lowering switch acts before the key switch  | 1212C-2503 |
|          | TOWN_ONO_TAGET       | The litting of lowering switch acts before the key switch  | controller |
| 2        | SRO_FAULT            | Wrong operation sequence of direction, interlock and   | 1212C-2503 |
|          | 0110_171021          | key switch   | controller |
|          |                      | Interlocking and accelerator operation sequence is   | 1212C-2503 |
| 3        | HPD_FAULT            | incorrect; Or after emergency reverse action, the  | controller |
|          |                      | accelerator does not return to home position   |            |
| 4        | WIRING_FAULT         | Throttle wiring fault  | 1212C-2503 |
|          | _                    | 3  | controller |
| 5        | THROTTLE_FAULT       | Throttle fault   | 1212C-2503 |
|          |                      |  | controller |
| 6        | PRECHARGE_FAULT      | Controller Fault   | 1212C-2503 |
|          |                      |  | controller |
| 7        | MAIN_DRIVER_FAULT    | Internal main contactor problem  | 1212C-2503 |
|          |                      | moman main semaster presion  | controller |
| 8        | MAIN_RELAY_WELDED    | Electric control internal contactor welded   | 1212C-2503 |
|          |                      | Elocate contact mornal contactor worder  | controller |
| 9        | MAIN_RELAY_DNC       | Electric control internal contactor does not close   | 1212C-2503 |
|          |                      | Ziodale della il illerina della dell | controller |
| 10       | BRAKE_OFF_FAULT      | Open circuit or coil short circuit in the internal drive of  | 1212C-2503 |
|          | BIV ((12_011_17(02)  | the electromagnetic brake  | controller |
| 11       | MOTOR_OVER_TEMPERA   | Motor over temperature   | 1212C-2503 |
|          | TURE                 | motor ever temperature   | controller |
| 12       | BATTERY_DISCONNECT_  | Battery cable connection problem   | 1212C-2503 |
|          | FAULT                | Battery caste controction prostom  | controller |
| 13       | BRAKE_ON_FAULT       | The EM brake internal driver short circuited or the coil   | 1212C-2503 |
|          | BIV 1112_011_1710E1  | is open circuited  | controller |
| 14       | CURRENT_SENSE_FAULT  | Electric control fault   | 1212C-2503 |
|          | OOKKENT_GENGE_F7.GET | Licotic control radio  | controller |
| 15       | HARDWARE_FAULT       | The electric control fails or the motor responds   | 1212C-2503 |
|          | 71/4(DVV/4(L_1/10L1  | incorrectly  | controller |
| 16       | SOFTWARE FAULT       | Electric control fault   | 1212C-2503 |
|          | 001 177/INE_17/IOE1  | 2.000.10 GOTINGT TAUK  | controller |
| 17       | PARAMETER_CHANGE_F   | Parameter change fault   | 1212C-2503 |
| 17       | AULT                 |  | controller |
| 18       | MOTOR SHORT          | motor short  | 1212C-2503 |
| 10       | WOTOI\_OHOI\T        | motor short  | controller |

| 19 | MOTOR_OPEN           | motor open  | 1212C-2503               |
|----|----------------------|---|--------------------------|
|    | CONTROLLER_OVERCUR   |   | 1212C-2503               |
| 20 | RENT                 | Electric control overcurrent                            | controller               |
|    | MOTOR_TEMP_HOT_CUT   |   | 1212C-2503               |
| 21 | BACK                 | Motor overcurrent cutback                               | controller               |
| 00 | CONTROLLER_OVERTEM   |   | 1212C-2503               |
| 22 | P_CUTBACK            | controller over temp cutback                            | controller               |
| 23 | CONTROLLER_UNDERTE   | controller under temp                                   | 1212C-2503               |
| 23 | MP                   | controller under temp                                   | controller               |
| 24 | CONTROLLER_SEVERE_   | controller severe over temp                             | 1212C-2503               |
| 24 | OVERTEMP             | controller severe over temp                             | controller               |
| 25 | OVERVOLTAGE_CUTBAC   | overvoltage cutback                                     | 1212C-2503               |
| 20 | K                    | over voltage outback                                    | controller               |
| 26 | SEVERE OVERVOLTAGE   | severe overvoltage                                      | 1212C-2503               |
|    | OLVERIC_OVERVOEITOE  | oover overveilage                                       | controller               |
| 27 | UNDERVOLTAGE_CUTBA   | Under voltage cutback                                   | 1212C-2503               |
|    | CK                   |   | controller               |
| 28 | SEVERE_UNDERVOLTAG   | severe under voltage                                    | 1212C-2503               |
|    | Е                    | -   | controller               |
| 29 | PARAMETER_FAULT      | electric control defective or parameter set fault       | 1212C-2503               |
|    |                      |   | controller               |
| 30 | GAGE_PDO_TIMEOUT     | Instrument communication time out                       | 1212C-2503               |
|    |                      |   | controller<br>1212C-2503 |
| 32 | PDO_TIMEOUT          | Tiller communication time out                           | controller               |
|    |                      |   | 1212C-2503               |
| 33 | LIFT_DRIVER_FAULT    | Driver 1 (J1-3) fault                                   | controller               |
|    |                      |   | 1212C-2503               |
| 34 | LOWER_DRIVER_FAULT   | Driver 2 (J1-11) fault                                  | controller               |
|    |                      |   | 1212C-2503               |
| 36 | BMS_PDO_TIMEOUT      | BMS communication timeout                               | controller               |
|    | EMR_SEQUENCING_FAUL  | Author Communication                                    | 1212C-2503               |
| 37 | Т Т                  | Action of emergency reverse switch before power on      | controller               |
| 20 | TILLER_HANDSHAKE_FAI | Handahaka hatusaan tillad amd alastiis assistat 5-200   | 1212C-2503               |
| 38 | LED                  | Handshake between tilled and electric control failed    | controller               |
|    |                      | The interlock switches from On to Off when the vertical | 1212C-2503               |
| 39 | COAST_SRO_FAULT      | traction switch acts before the key switch or when the  | controller               |
|    |                      | vertical walking switch is closed                       |                          |
| 40 | PUSH_SRO_FAULT       | Push the action of switch before power on               | 1212C-2503               |
|    |                      | - dell'allo dellett et switch before power off          | controller               |
| 80 | Mode fault           | Tiller tortoise speed button fault                      | tiller                   |
| 81 | Lift fault           | Lift button fault                                       | tiller                   |
| 82 | Lower fault          | Lower button fault                                      | tiller                   |
| 83 | BMS Communication    | Lithium battery communication outage                    | tiller                   |

|    | Outage                   |                              |               |
|----|--------------------------|------------------------------|---------------|
| 90 | Over Voltage             | battery over voltage         | Li-on battery |
| 91 | Over Discharge           | battery over discharge       | Li-on battery |
| 92 | Communication Outage     | battery communication outage | Li-on battery |
| 93 | Under Voltage            | battery Under Voltage        | Li-on battery |
| 94 | Over Current             | battery overcurrent          | Li-on battery |
| 95 | Over Temperature Protect | battery severe over temp     | Li-on battery |
| 96 | Temperature Protect      | battery over temp            | Li-on battery |

# 1212E Fault code measures ( EN1175 )

|    | LE i dan codo | Illeasules ( EIV I I           | 101  |  |
|----|---------------|--------------------------------|--|--|
| No | Error Code    | Fault Name                     | Possible cause   | Fault Source                               |
| 1  | 11-1          | Severe Under voltage           | Controller defective Battery defective                                 | 1212E<br>Controller<br>1212E<br>Controller |
| 2  | 12-1          | Under voltage<br>Cutback       | Incorrect battery voltage Main relay defective Controller AD defective | 1212E<br>Controller                        |
| 3  | 13-1          | Severe                         | Incorrect battery voltage  | 1212E                                      |
| 4  | 13-2          | Overvoltage                    | Main relay defective Controller AD defective                           | Controller                                 |
| 5  | 14-1          | Overvoltage<br>Cutback         | Incorrect battery voltage Main relay defective Controller AD defective | 1212E<br>Controller                        |
| 6  | 15-1          | Controller Severe Under temp   | Temperature sensor defective  Low ambient temperature                  | 1212E<br>Controller                        |
| 7  | 16-1          | Controller Over temp Cutback   | Temperature sensor defective High current for a long time              | 1212E<br>Controller                        |
| 8  | 17-1          | Controller Severe<br>Over temp | Temperature sensor defective   | 1212E<br>Controller                        |
| 9  | 21-1          |                                |  |  |
| 10 | 21-2          |                                | Throttle wiring fault Incorrect throttle type setting                  | 1212E                                      |
| 11 | 21-3          | Throttle Fault                 | Incorrect throttle operation Steering Angle Pot wiring fault           | Controller                                 |
| 12 | 21-4          |                                |  |  |
| 13 | 22-1          | HPD Sequencing                 | Incorrect throttle operation Throttle defective                        | 1212E<br>Controller                        |
| 14 | 23-1          | Main Relay<br>Welded           | Main relay defective   | 1212E<br>Controller                        |
| 15 | 24-1          | Main Relay Did                 | Main relay defective   | 1212E                                      |
| 16 | 24-2          | Not Close                      | Incorrect relay pull in voltage setting                                | Controller                                 |
| 17 | 25-1          | Main Driver Fault              | Main driver defective  | 1212E                                      |
| 18 | 25-2          |                                |  | Controller                                 |
| 19 | 26-1          | Pre charge                     | Pre charge PTC defective   | 1212E                                      |
| 20 | 31-1          | Failed Stall Detected          | Pre charge PTC defective   | Controller 1212E                           |
|    |               |                                |  | Controller                                 |

| 22 | 32-1 |                           |   | 1212E               |
|----|------|---------------------------|---|---------------------|
| 23 | 32-2 | - Motor Short             | Motor Short                                       | Controller          |
| 24 | 33-1 | Matar Oner                | M.L. O  | 1212E               |
| 25 | 33-2 | Motor Open                | Motor Open  | Controller          |
| 26 | 34-1 | EM brake failed<br>To Set | EM brake defective                                | 1212E<br>Controller |
| 27 | 41-1 | Push SRO                  | Incorrect operation sequence Controller defective | 1212E<br>Controller |
| 28 | 42-1 | Interlock SRO<br>Fault    | Incorrect operation sequence Controller defective | 1212E<br>Controller |
| 29 | 43-1 | Low BDI                   | Battery over discharged                           | 1212E<br>Controller |
| 30 | 44-1 |                           |   |                     |
| 31 | 44-2 | Canad                     |   | 40405               |
| 32 | 44-3 | Speed<br>Supervision      | Speed is out of allowed range                     | 1212E<br>Controller |
| 33 | 44-4 | Caparviolon               |   | Controller          |
| 34 | 44-5 |                           |   |                     |
| 35 | 51-1 | Over Current<br>Fault     | Controller defective Current sensor defective     | 1212E<br>Controller |
| 36 | 52-1 | Current Sense             | Company a second linear singuity defeative        | 1212E               |
| 37 | 52-2 | Fault                     | Current sampling circuit defective                | Controller          |
| 38 | 53-1 |                           |   |                     |
| 39 | 53-2 | Driver Fault              | Driver open or short                              | 1212E               |
| 40 | 53-3 | Driver Fault              | Incorrect parameter settings                      | Controller          |
| 41 | 53-4 |                           |   |                     |
| 42 | 54-1 |                           |   |                     |
| 43 | 54-2 |                           | Incorrect operation sequence                      | 40405               |
| 44 | 54-3 | PUMP SRO Fault            | Switch defective                                  | 1212E<br>Controller |
| 45 | 54-4 |                           | Incorrect parameter settings                      | Johnson             |
| 46 | 54-5 |                           |   |                     |
| 47 | 55-1 |                           | EMR switch defective                              |                     |
| 48 | 55-2 | EMR SRO Fault             | Incorrect operation sequence                      | 1212E<br>Controller |
| 49 | 55-3 |                           | Incorrect parameter settings                      |                     |
| 50 | 56-1 |                           |   |                     |
| 51 | 56-2 | Creep SRO Fault           | Incorrect operation sequence Cost                 | 1212E               |
| 52 | 56-3 | Orcop onto i ault         | moon oot operation sequence cost                  | Controller          |
| 53 | 56-4 |                           |   |                     |

| 54 | 61-1               |                                |  |                     |
|----|--------------------|--------------------------------|--|---------------------|
| 55 | 61-2               | PDO Timeout                    | CAN bus too heavy  | 1212E<br>Controller |
| 56 | 61-5               |                                | Incorrect parameter setting  | Controller          |
| 57 | 62-SDO Abort<br>ID | PDO Mapping<br>Error           | Incorrect variable data length Incorrect access mode Incorrect CAN index   | 1212E<br>Controller |
| 58 | 71-1               |                                |  |                     |
| 59 | 71-2               |                                |  |                     |
| 60 | 71-3               | Hardware Fault                 | MOSFET defective   | 1212E               |
| 61 | 71-4               |                                | Micro defective  | Controller          |
| 62 | 71-5               |                                |  |                     |
| 63 | 81-Parameter index | Parameter Out Of Range         | Incorrect variable data  | 1212E<br>Controller |
| 64 | 82-1               |                                |  |                     |
| 65 | 82-2               |                                |  |                     |
| 66 | 82-3               | Parameter Fault                | Incorrect parameter settings FRAM defective  | 1212E<br>Controller |
| 67 | 82-4               |                                | 1 IVAIN delective  | Controller          |
| 68 | 82-6               |                                |  |                     |
| 69 | 83-Block num       |                                |  |                     |
| 70 | 83-2               |                                |  |                     |
| 71 | 83-3               | NV Failure                     | FRAM operation failed  | 1212E<br>Controller |
| 72 | 83-4               |                                |  | Controller          |
| 73 | 83-5               |                                |  |                     |
| 74 | 84-code            | Supervision                    | Cross check failed   | 1212E<br>Controller |
| 75 | 80                 | Mode fault                     | Tiller Turtle speed button failure, Turtle speed button detected closed before power on.   | Tiller              |
| 76 | 81                 | Lift fault                     | Rise button failure, the rise button is detected as being pressed before the power is turned on.   | Tiller              |
| 77 | 82                 | Lower fault                    | Faulty drop button, the drop button is detected as being pressed before the power is turned on.  | Tiller              |
| 78 | 83                 | BMS<br>Communication<br>Outage | Lithium battery communication timeout, 1. Lithium battery BMS damaged. 2. Lithium battery to handle Tiller communication line broken. 2. handle Tiller communication module damaged. | Tiller              |

| 79 | 84 | Throttle FAULT                  | The gas pedal is not in the neutral position before the code is entered, and the gas pedal needs to be reset to clear the fault.   | Tiller             |
|----|----|---------------------------------|--|--------------------|
| 80 | 85 | Controller Communication Outage | Controller communication lost  | Tiller             |
| 82 | 86 | Lift system failure             | Pump station output continuous operation, lifting system failure, possibly rising micro switch failure   | Tiller             |
| 83 | 90 | Over Voltage                    | Battery voltage is too high. 1, may be the charger overcharge. 2, battery BMS problems. 3, the vehicle for a long time downhill, caused by the feedback current charging.  | Lithium<br>Battery |
| 84 | 91 | Over Discharge                  | 1, lithium batteries are not used for a long time, resulting in low battery power. 2, overuse.   | Lithium<br>Battery |
| 85 | 92 | Communication Outage            | Battery communication timeout, communication timeout with controller   | Lithium<br>Battery |
| 86 | 93 | Under Voltage                   | Battery voltage is too low, 1, long-term storage, not in time to charge. 2, the battery internal cell damage, resulting in the inability to charge into the power.   | Lithium<br>Battery |
| 87 | 94 | Over Current                    | 1, the use of equipment is not in accordance with the original program set by the controller to run. 2, after the replacement of the controller, the parameters do not match. 3, the lithium battery current detection problems. | Lithium<br>Battery |
| 88 | 95 | Over Temperature Protect        | .Severely high battery temperature, use or transport environment, causing severe internal high temperature of the battery.   | Lithium<br>Battery |
| 89 | 96 | Temperature<br>Protect          | High battery temperature, use or transport environment, causing high temperature inside the battery.   | Lithium<br>Battery |

## 3 Drive/brake system

#### 3-1 Overview

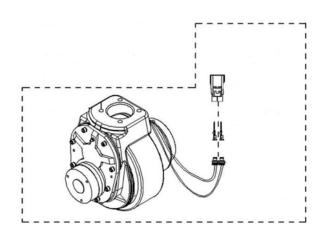
## 3-1-1 Component

The drive/brake system includes the following:

- 1 The drive motor controlled by the controller transmits the rotational force to the drive shaft (electricity mechanical power) (3-2)
- 2 The drive shaft converts the rotational force transmitted from the drive motor into torque and speed suitable for driving through its gear set, and sends them to the corresponding wheels (mechanical power). They also include service brakes, which use a controller to control electromagnetic brakes to generate braking power (friction) (3-3)
- 3 The accelerator sends a CAN number to the drive motor controller to accelerate the motor (CAN signal) (3-4)

### 3-2 Drive assembly

## 3-2-1 appearance



## 3-2-2 How does this work

On the electric side, the driving motors rotate their drive wheels so that the vehicle can move forward/backward

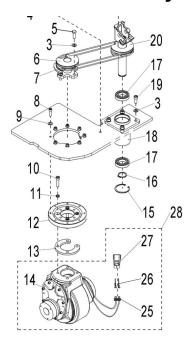
Controlled by the controller

Each drive motor is connected to the controller via MI and M2 lines. The controller runs the drive motor based on input from multiple switches and sensors and internal parameter Setting

When the following conditions are met, the drive motor operates:

- 1. Open the key and emergency stop switch to supply power to the controller.
- 2. Move the tiller to the operating area
- 3 determine the driving direction,
- 4 Twist the accelerator on the tiller

## Removal/assembly of drive assembly



#### Preliminary steps

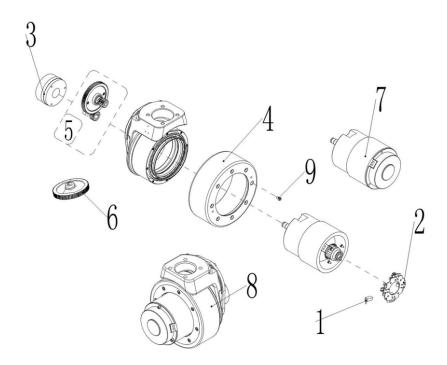
- 1. Safely park the vehicle and remove the shell
- 2. Close key and emergency stop switch.
- 3. Disconnect the battery connector.

#### procedure

- 1. Remove steering wire rope assembly (7).
- 2 remove the steering shaft screw (5) and remove the steering shaft (6)
- 3. Lift the whole vehicle with the weight of 5 8 5 KG.
- 4. Disconnect the connecting terminals of the driving motor and the electromagnetic brake, and put the vehicle into a stop.
- 5. Remove the fixing screw (8) of the drive assembly and lift the whole vehicle to remove the drive assembly.
- 6. Remove the slewing support fixing screw (1 0) to remove the slewing support and connecting plate (13)

Follow the steps in reverse order to install the drive assembly

## 3-2-3 Drive motor disassembly/assembly and test



## Disassembly/assembly

- 1. Remove the fixing screw of the electromagnetic brake and remove the electromagnetic brake (3)
- 2 Remove the electromagnetic brake gear.
- 3. Remove the drive housing screw and remove the housing.
- 4. Loosen and exit the motor fixing screw.
- 5. Set up the motor in the air and press the motor downward.

Perform the above steps in reverse order to assemble the drive motor.

Note: Before reassembling the motor, you can test its components as follows.

#### motor test

- 1 The resistance between MI and M2 is measured using a milliohmmeter. Nominal resistance: 0.4  $\Omega$
- 2 Test insulation at 1000 Vac and Min. 10 m Q use insulation tester. If there is a problem with insulation, please replace it with a new motor

## Carbon brush removal/assembly

- I. Remove the carbon brush housing fixing screw
- 2. Remove the brush holder assembly.
- 3. Remove the fixing screws of the brush and brush holder.
- 4. Press the spring upward and take out the carbon brush.

Assemble the brush holder assembly by following the steps in reverse order.

### 3-2-4 Drive wheel removal/installation

Preliminary steps

- 1. Safely park the vehicle and remove the shell
- 2. Close key and emergency stop switch.
- 3. Disconnect the battery connector. program
- 1. Use the crane to lift the vehicle safely.
- 2. Disconnect the connection line of the drive motor.
- 3. Loosen and exit the driving wheel fixing screw (9)
- 4. Push out the drive wheel with screws.

Perform the above steps in reverse order to assemble the drive wheels.

## 3-3 Service braking system

### 3-3-1 Overview

The brake system is composed of a drive controller, an electromagnetic coil and a brake disc, and the brake is an expansion spring compression type.

### 3-3-2 How does this work

In terms of electric power, the drive controller controls the pull-in of the electromagnetic brake so that the vehicle can brake

Controlled by the controller

Each electromagnetic brake is connected to the controller through a wire. The controller operates the electromagnetic brake closing and closing time according to the input from multiple switches and sensors and internal parameter settings«

When the following conditions are met, the electromagnetic brake is engaged:

- 1 Turn on the key and the emergency stop switch to supply power to the controller,
- 2 Move the tiller to the operating area,
- 3 The electromagnetic brake is engaged,

### 3-3-3 test

- 1 Use a milliohm meter to measure the resistance between the electromagnetic brakes. Rated resistance: 0.4Q
- 2 Test the insulation at 1000 Vac and Min. 10MO uses an insulation tester.

If there is a problem with the insulation, replace the electromagnetic brake with a new one.

## 3-3-4 Removal/installation of electromagnetic brake

## Preliminary steps

- 1 Park the vehicle safely and remove the shell
- 2 Turn off the key and emergency stop switch.
- 3 Disconnect the battery connector.

# procedure

- I Use a hoist to lift the vehicle safely.
- 2 Disconnect the connecting wire of the electromagnetic brake.
- 3 Loosen and remove the electromagnetic brake fixing screws
- 4 Take out the electromagnetic brake and related components.

Perform the above steps in reverse order to assemble the electromagnetic brake.

# 3-4 Troubleshooting

# 3-4-1 Drive motor

| Problem                                  | Possible causes   |
|--|---|
| Drive motor does not work                | Switch not off (battery connector, key switch, seat switch, f / R           |
|  | switch or parking brake switch):  |
|  | Turn off the switch. If it still fails to operate, use a voltmeter to       |
|  | test the power supply of the control panel and the current of               |
|  | each switch.  |
|  | However, turn on the service brake switch.                                  |
|  | Bad signal. Fuse blown:   |
|  | Check the battery connections. Check the connection of the                  |
|  | battery connector. Check fuses, drivers and logic. Replace                  |
|  | the fuse if it is blown.  |
|  | Check whether the drive motor and control panel may cause the fuse to blow. |
|  | Some of the reasons are:  |
|  | Working under excessive load, current limit is too high                     |
|  | Low battery voltage:  |
|  | Check the battery terminal voltage. If it is too low, charge the            |
|  | battery.  |
| Drive motor does not work                | Excessive wear of the carbon brush (from the spring                         |
|  | compression plate to the lowest position of the carbon brush).              |
| Traction does not operate during normal  | Defects in the brake cause excessive resistance. Increased                  |
| operation, but hydraulic operation is    | heat causes motor stalling. Check brake adjustment.                         |
| normal                                   | Overweight Traction Load: Reduce Duty Cycle Load.                           |
| Traction and hydraulic pressure will not | The lift car is equipped with too small battery:                            |
| last the whole normal operation period   | Battery not fully charged during battery charging:                          |
|  | Check whether the battery is charged  |
|  | Check the battery charger for failure.                                      |
|  | The battery replacement interval is too long or the cooling                 |
|  | time of the replacement battery is too short.                               |
|  | The battery has one or more defective single cells, causing                 |
|  | the rated capacity and capacity of the battery to be lower than             |
|  | normal:   |
|  | Due to the failure of the drive system, the drive system                    |
|  | consumes too much battery power.  |
|  | Check the brake adjustment. Check the wheel bearing, axle                   |
|  | and other mechanical parts for correction to eliminate the                  |
|  | fault. Change to a tire with less friction                                  |
|  | The hydraulic system consumes too much battery power due                    |
|  | to lifting and tilting faults, or the hydraulic conditions of the           |
|  | duty cycle are incorrect:   |
|  | Reduce the setting of the hydraulic relief valve to the capacity            |
|  | used only.  |

| Replace with a smaller hydraulic pump.                          |
|---|
| Check the mast for restrictions during operation.               |
| After a work shift, the forklift's working capacity exceeds its |
| designed capacity without available power:                      |
| Battery or control panel wires in contact with the vehicle      |
| frame:  |
| Carry out continuity test and move wire contact.                |
| Remove the lead in sequence until the fault is cleared.         |
| The fault will break at the end of the wire                     |
| Dirty motor: clean carbon powder in time                        |
| Wet motor: motor wet  |
| The battery is not fully charged or poor:                       |
| Charge the battery.   |
| Faults in the drive motor, control panel or drive line:         |
| Check the vehicle speed in both directions and the steering     |
| speed limit proximity switch. If you need to adjust the control |
| panel, adjust according to the corresponding section of         |
| Section 2 Electrical System.                                    |
| If the drive motor fails, test the motor components             |
|   |

# 3-4-2 Drive axle

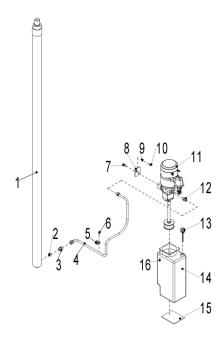
| Problem                                   | Possible causes  |  |
|---|--|--|
| Noise or vibration in the transmission    | Incorrect oil level:   |  |
|   | Meet the correct oil level   |  |
|   | Use non-standard oil:  |  |
|   | Replace the oil with standard oil.                                 |  |
|   | Gear damaged or dented:  |  |
|   | Replace the gear.  |  |
|   | Bearing damage:  |  |
|   | Replace the bearing.   |  |
|   | Loose mounting bolts:  |  |
|   | Apply thread compound to the threads of the bolts and retighten to |  |
|   | the specified torque.  |  |
| Noise or vibration in the brake disc pack | Use non-standard oil or friction materials:                        |  |
|   | Replace oil or friction materials with standard materials.         |  |
|   | Friction plate wear:   |  |
|   | Replace the friction plate.  |  |
| Leakage of installation part              | Loose mounting bolts:  |  |
|   | Apply thread compound to the threads of the bolts and retighten to |  |
|   | the specified torque.  |  |

# 4 The hydraulic system

#### 4-1 overview

The hydraulic system is composed of working oil pump, lifting cylinder and pipeline. Hydraulic oil is supplied by a pump directly connected to the motor. The pump sends the hydraulic pump to the cylinder

## 4-1-1 component



The hydraulic system uses pressurized hydraulic oil from the main hydraulic pump to operate the lifting cylinders and draw out the oil discharged from these cylinders.

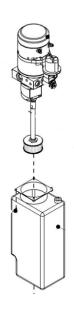
- 1 The pump motor controlled by the controller drives the main hydraulic pump. [Section 4-2]
- 2 The main hydraulic pump uses the rotational force output from the motor to pressurize the oil in the hydraulic oil tank and deliver the oil to the lifting cylinder. [Section 4-3]
- 3 The hydraulic oil tank stores the hydraulic oil returned from the lifting cylinder. The stored oil is sucked by the main hydraulic pump for reuse. [Section 4-5]

#### Hydraulic oil circulation

The hydraulic oil tank stores hydraulic oil, which is supplied to the main hydraulic pump through a filter. The main hydraulic pump pressurizes the supplied oil and sends it to the lifting cylinder. When hydraulic oil is received, these systems perform their functions and then drain the waste oil to the tank through a return filter.

# 4-2 Pump station assembly

# **4-2-1 Appearance and specifications**



| Item             | Specification |
|------------------|---------------|
| Power            | 0.8KW         |
| Speed            | 1618rpm       |
| Frequency        | 55.5hz        |
| Insulation level | Н             |

#### 4-2-2 test

The pump motor transmits power to the main hydraulic pump electrically to pump hydraulic oil to operate the hydraulic system.

The pump motor is connected to the controller through a motor contactor. The controller operates the pump motor contactor based on inputs from multiple switches and sensors and internal parameter settings.

When the following conditions are met, the pump motor runs:

The key emergency stop switch is turned off.

The limit switch and the up button are closed.

Pump motor contactor suction



# **Pump motor contactor detection:**

For the pump motor contactor, according to the figure. And check if it measures the specified value.

# 4-2-3 Removal/installation of pump motor and hydraulic pump

Note: When assembling and disassembling the hydraulic pump, do not apply any pressure to the motor

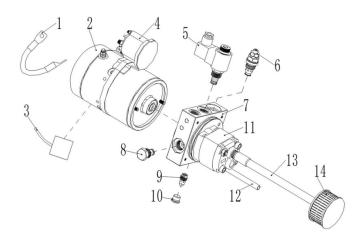
# Pressurized hydraulic fluid can cause severe burns and may even result in amputation. Before performing the following steps, make sure that the pressure has been released from the system.

#### procedure

- 1. Disconnect the cable from the motor B-and pump motor contactor terminals.
- 2. Disconnect the wiring harness of the pump motor contactor and the lowering solenoid valve.
- 3. Disconnect the hose from the hydraulic pump.
- 4. Remove the fixing screws of the pump station assembly, and take out the pump station assembly.
- 5. Follow the above steps in reverse order to install the pump motor.
- 6. Fill the hydraulic oil tank according to the specifications given in section 1-6.

The pressure of the safety valve has been adjusted before leaving the factory, and users are not allowed to adjust and disassemble at will.

## 4-2-4 Pump motor disassembly/assembly and testing



- 1. Disconnect the connection of the pump motor contactor and remove the contactor.
- 2. Loosen the fixing screws of the pump motor and pump.
- 3. Remove the motor from the vertical pump station upwards.
- 4. Perform the above steps in reverse order to assemble the pump motor. Note: Before reassembling the motor, you can test its parts as followso

#### Motor test

- I Use a milliohm meter to measure the resistance between the electromagnetic brakes. Rated resistance: 0.40
- 2 Test the insulation at 1000 Vac and Min. 10MQ uses an insulation tester.

If there is a problem with the insulation, please replace the pump motor with a new one

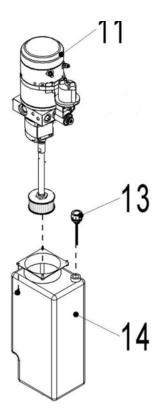
Pump motor carbon brush disassembly/assembly

- 1 Remove the fixing screws of the carbon brush housing
- 2 Remove the carbon brush holder assembly.
- 3 Remove the fixing screws of the carbon brush and the carbon brush holder.
- 4 Squeeze the leaf spring upward and take out the carbon brush.

Perform the above steps in reverse order to assemble the carbon brush holder assembly.

# 4-3 Hydraulic oil tank and filter

## 4-3-1 appearance



## 4-3-2 Replacement of hydraulic fluid and filter

Preliminary steps

- 1. When the fork reaches the top, press the drop button several times to eliminate residual pressure in the hydraulic system
- 2. Open the case and disconnect the battery.
- 3. Prepare and oil pan.

# A Danger

Pressurized hydraulic fluid can cause severe burns and may even result in amputation.

Refore performing the following steps, make sure

Before performing the following steps, make sure that the pressure has been released from the system.

#### procedure

- 1. Remove the pump station assembly (see 4-2-3 for details).
- 2. Remove the 4 fixing screws of the fuel tank and pump station.
- 3. Loosen the fastening screw of the fuel tank.
- 4. The hydraulic oil can be poured out after pulling up the pump station.
- 5. Replace the filter as needed.

Perform the above steps in reverse order to assemble the fuel tank and filter.

# 4-4 troubleshooting

# 4-4-1 Pump motor

| Problem                             | Possible causes   |
|-------------------------------------|---|
| Hydraulic pump motor does not work. | Poor connection or fuse blown.                              |
|                                     | Check battery connections.                                  |
|                                     | Check the key fuse.   |
|                                     | Check whether the motor of the hydraulic pump may cause     |
|                                     | the fuse to break.  |
|                                     | Key switch, upper limit switch, line contactor not closed.  |
|                                     | Turn off the key switch. Use a multi meter to check the     |
|                                     | power flow through the key switch, the line contactor coil  |
|                                     | and the line contactor. The key switch must be turned off.  |
|                                     | Insufficient voltage.                                       |
|                                     | Charge or replace the battery.                              |
|                                     | Check that the cable terminals are tightly aligned with the |
|                                     | battery terminals and the control panel connector.          |
|                                     | Check whether the wires inside the cable are broken.        |
|                                     | Incorrect operation of lifting and driving systems.         |
|                                     | During battery charging operation, the battery is not fully |
|                                     | charged.  |
|                                     | Hydraulic system consumes too much battery power due        |
|                                     | to incorrect lifting or hydraulic control for work cycles.  |
|                                     | Hydraulic pump motor overheating.                           |
|                                     | If the motor temperature reaches 155 degrees C (311         |
|                                     | degrees F)  |

# 4-4-2 Hydraulic pump

| Problem                              | Possible causes   |
|--------------------------------------|---|
| Noise in the pump.                   | The oil level is low.                                   |
|                                      | The oil is very thick (viscosity is too high)           |
|                                      | The pump inlet line is limited.                         |
|                                      | Wear parts in the pump.                                 |
|                                      | The oil is dirty.                                       |
|                                      | Air leaks into the inlet line.                          |
| The oil temperature is too high.     | The oil level is low.                                   |
|                                      | There are restrictions on the passage.                  |
|                                      | The oil is too thin.                                    |
|                                      | There is air leakage in the system.                     |
|                                      | The pump is too worn.                                   |
|                                      | The system is operating under too high pressure.        |
| Leakage at pump shaft seal.          | The shaft seal is worn.                                 |
|                                      | Internal wear of pump body.                             |
|                                      | Operation with a low oil level in the tank can cause    |
|                                      | suction on the seal.                                    |
|                                      | During installation, the seal is cut at the part of the |
|                                      | pump or keyway.   |
|                                      | The sealing lip is dry and hardened by heat.            |
| The pump is unable to deliver fluid. | The oil content in the tank is low.                     |
|                                      | The pump inlet line is limited.                         |
|                                      | There is air leakage in the pump inlet pipeline.        |
|                                      | Loose bolts.  |
|                                      | Defect in suction line of bay.                          |
|                                      | The viscosity of the oil is wrong.                      |
|                                      | The pump is too worn.                                   |
|                                      | Pump shaft failure                                      |
|                                      | The bolts for the pump do not have the correct          |
|                                      | torque.   |

# 5 Lifting/tilting/auxiliary system

# 5-1 Overview

# 5-1-1 Component

The lifting system is powered by the main hydraulic pump.

Fork: Two fork-shaped objects to support the load

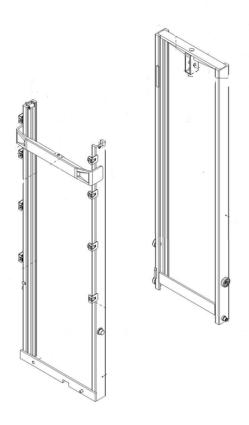
Chain: the part that lifts the bracket and mast

Lifting cylinder: single-acting cylinder pulls back the chain of the bracket

Mast: the vertical structure at the front of the forklift, which extends and retracts to lift and lower the load

## 5-2 Mast

## 5-2-1 appearance



#### Mast lift

The mast assembly uses two masts and a single acting cylinder to lift the load. Rollers mounted on the inside and outside of the fork and the mast facilitate these up/down movements.

#### Cylinder

After receiving the hydraulic oil from the pump station, the rod of the cylinder extends upward to push the internal mast, while the fork is pulled by the lifting chain, which is connected to the outer mast to lift with the chain.

#### Lower

If the operator controls the lever to open the outlet port in the poppet of the multiway valve, the oil output from the standard cylinder will begin to flow out by gravity.

When the oil is drained, the cylinder rod and the attached inner Mast will retract.

When the inner Mast is lowered, the tension of the lifting chain will be relaxed and the bracket will also be lowered.

## 5-2-2 Fork

#### A Fork Inspection

Forks should be checked at least every 12 months. If the vehicle is used in multiple shifts or heavy work, it should be checked every 6 months.

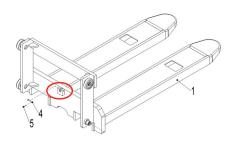
- 1. Check forks carefully for cracks. Pay particular attention to the rear section, all welding areas and mounting brackets. Forks with cracks should be replaced
- 2. Check the angle between the upper surface of the fork blade and the front surface of the fork handle.

If the angle exceeds 93 degrees or deviates from the original angle beyond 90 degrees by more than 3 degrees, the fork shall be removed from service.

B chain tension adjustment

- I. Fill IOcm-thick sleepers under the forks and lower the forks completely.
- 2. Disconnect the chain and fork.
- 3. Slowly raise the main frame to make the fork frame separate from the main frame and take out the fork.
- 4. Perform the above steps in reverse order to install the fork.

Note: During the disassembly process, check the fork and fork frame, and replace any parts that may be damaged, cracked or excessively rusted.



#### 5-2-3 Chain

#### A. Chain wear check

To check the chain wear, you must first find the chain spacing

- 1. Lift the bracket enough to apply tension on the lifting chain.
- 2. Place the stationary pointer of the chain wear gauge on the upper pin of the chain link.
- 3. Place the sliding pointer on the lower pin of the chain link.
- 4. Make sure to line up the two pointers at the same position on the two pins to get an accurate reading.
- 5. Fix the sliding pointer in place and read the scale on the meter to find the chain pitch.

#### After finding the chain distance, start the wear check:

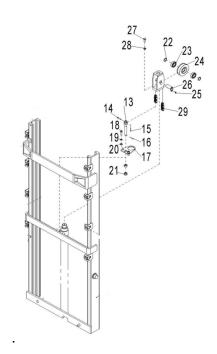
- 1. Place the sliding pointer on one of the three boxes at the bottom of the meter scale.
- 2. Place the pointer window on the square containing the chain spacing found above
- 3. Fix the measuring instrument on the other side of the lifting chain again so that the fixed pointer rests on the upper pin of one of the chain links.
- 4. Lean the entire length of the indicator on the lifting chain and move the sliding pointer until it aligns with the upper pin of the other link, keeping the pointer window on the correct square found in step 2.
- 5. If the chain is too worn, replace the lifting chain

#### B. Chain tension check

- 1. Lower the forks to the lowest level.
- 2. Gently push the lifting chain by hand to check the tension. If it does not feel tight, please follow the adjustment below The entire program operation.
- 3. Raise the fork and place a 10 cm-thick sleeper under it.
- 4. Lower the fork onto the sleeper block to release tension from the chain.
- 5. Tighten or loosen the lock nut at the junction of the chain and the main frame to increase or decrease the chain tension as needed.
- 6. After the adjustment is complete, put the thread glue on the threads of the lock nut.

#### Lifting chain removal/installation

- 1. Raise the fork and place sleepers under it.
- 2. Lower the forks onto the sleepers to release tension from the main lifting chain.
- 3. After removing the cotter pin (5), pull out the cotter pin (4) and remove the chain from the chain anchor.
- 4. Remove the bolts and washers connecting the chain and the main frame, and then take out the chain.
- 5. Perform the above steps in reverse order to install the main lifting chain.
- 6. Check that the chain has the correct tension.



# 5-2-4 Lifting cylinder

Cylinder removal/installation

- 1. Raise the fork and place sleepers under it.
- 2. Lower the forks onto the sleepers to release tension from the main lifting chain.
- 3. Remove the chain
- 4. Disconnect the oil pipe connected to the oil cylinder.
- 5. Remove the relevant components of the sprocket (24)
- 6. Remove the cylinder fixing plate (17).
- 7. Take out the cylinder upwards

Perform the above steps in reverse order to install the cylinder.

5-3 Troubleshooting

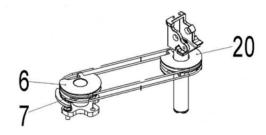
| Problem                       | Possible causes  |
|-------------------------------|--|
|                               | There is a leak that causes air to enter the hydraulic system on the inlet |
|                               | side of the hydraulic pump   |
| The hydraulic system will not | Emergency descent valve opens manually.                                    |
| lift the load.                | Too much wear on hydraulic pump  |
|                               | .Incorrect load (too heavy).   |
|                               | Mast does not align with other lifting parts and cannot move freely.       |
|                               | The moving mast part does not have enough lubricant.                       |
|                               | Bracket or Mast rollers (bearings) are worn and do not move (jam)          |
|                               | Insufficient oil supply for lifting cylinder.                              |
|                               | Poor sealing of lifting cylinder   |
| Lifting cylinder extension is | Mast does not align with other lifting parts and cannot move freely.       |
| too slow.                     | The moving mast part does not have enough lubricant.                       |
|                               | Bracket or Mast roller (bearing) worn and stationary (stuck)               |
|                               | Descent spool damage and contamination                                     |
| Mast does not be lowered      | Damaged or bent lifting cylinder.  |
| completely or at all.         | Load drum defective (bearing) or incorrectly adjusted.                     |
|                               | There is not enough lubricant in the moving mast area.                     |
|                               | Air in hydraulic system.   |
|                               | Mast does not align with other lifting parts and cannot move freely.       |
| Fork not lowered properly.    | The transport chain needs to be adjusted.                                  |
|                               | The moving mast part does not have enough lubricant.                       |
|                               | Forks or mast rollers (bearings) are worn and must not be moved            |
|                               | (stuck).   |

# 6 Steering System

#### 6-1 Overview

The steering system is a set of devices that steer the vehicle left or right. In this vehicle model, the steering system is mechanically structured and consists of a tiller rotation shaft (20) and a drive rotation shaft (6), which are connected by a steel wire chain (7).

## 6-1-1 appearance



# 6-1-2 Operation

#### A. Steering control mechanism

Once the tiller steering shaft (20) rotates, the drive steering shaft (6) is connected to the tiller steering shaft with a wire rope (7). The wire rope is divided into two upper and lower wires to connect them.

#### B. Neutral position

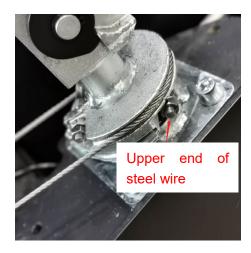
When the steering shaft of the tiller is in neutral, the wire rope connecting them is in a non-stressed state C. Turn left

When the steering shaft of the tiller rotates, the lower wire rope connecting them rotates, and at the same time, the steering shaft is driven to rotate. If the rotation is not synchronized, please tighten the lower wire rope.

#### D. Turn right

When the steering shaft of the tiller rotates, the upper wire rope connecting them rotates, and at the same time, the steering shaft is driven to rotate. If the rotation is not synchronized, please tighten the upper wire rope.





# 7 Schematic diagram

# 7-1 Hydraulic schematic

a.

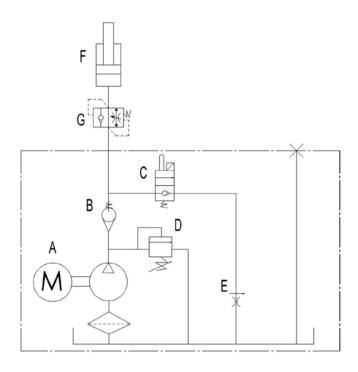


Table 3: Hydraulic Symbol Description

| No | Code | Item                                      | No | Code | Item           |
|----|------|---|----|------|----------------|
| 1  | Α    | Hydraulic power unit (motor and oil pump) | 5  | E    | Throttle valve |
| 2  | В    | Check valve                               | 6  | F    | Cylinder       |
| 3  | С    | Solenoid valve                            | 7  | G    | Safety valve   |
| 4  | D    | Relief valve                              |    |      |                |

b.

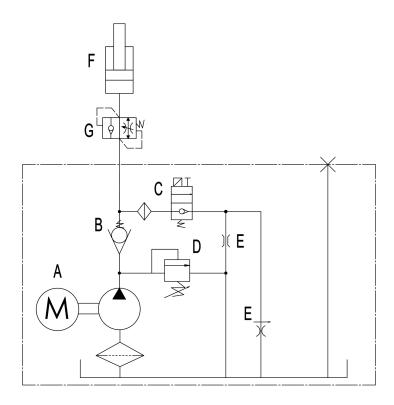
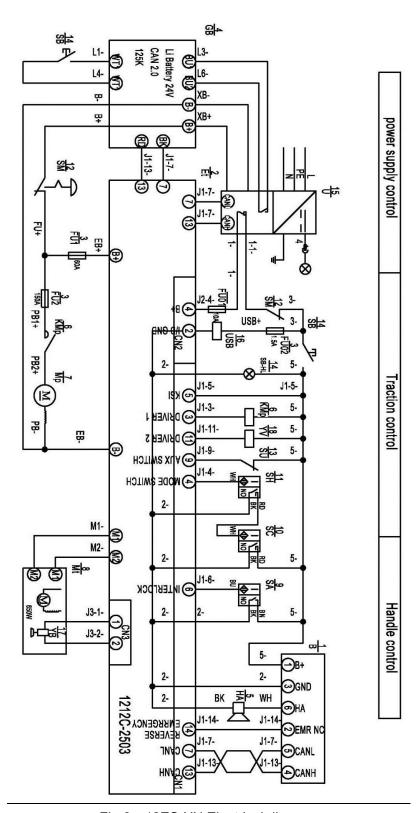


Table 4: Hydraulic Symbol Description

| Code | Item                 | Code | Item           |
|------|----------------------|------|----------------|
| Α    | Hydraulic power unit | Е    | Throttle valve |
| В    | check valve          | F    | Cylinder       |
| С    | Solenoid valve       | G    | Safety valve   |
| D    | Relief valve         |      |                |

# 7-2 Electrical schematic

# a. circuit diagram



FU1: 60 A FU2: 150 A FU01: 10 A FU02: 1.5 A

Fig 6: 12ES-XN Electrical diagram

<u>Table 5:</u> Explanation of Electrical Symbols

| No | Code | Item               | No | Code | Item                        | No | Code | Item                      |
|----|------|--------------------|----|------|-----------------------------|----|------|---------------------------|
| 1  | В    | Tiller             | 7  | MP   | Pump motor                  | 13 | SU   | Height limit micro switch |
| 2  | Et   | Controller         | 8  | MT   | Traction motor              | 14 | SB   | Button switch             |
| 3  | FU   | Fuse               | 9  | SA   | Inter lock                  | 15 | U    | Charger                   |
| 4  | GB   | Battery            | 10 | SC   | Lifting speed limit switch  | 16 | USB  | USB                       |
| 5  | НА   | Horn               | 11 | SH   | Steering speed limit switch | 17 | YB   | Electromagnetic brake     |
| 6  | KMP  | Oil pump contactor | 12 | SM   | DC power switch             | 18 | YV   | Lowering solenoid valve   |

#### b. Circuit Diagram (EN1175:2020)

FU1:60 A

FU2: 150 A

FU01: 10 A

FU02: 1.5 A

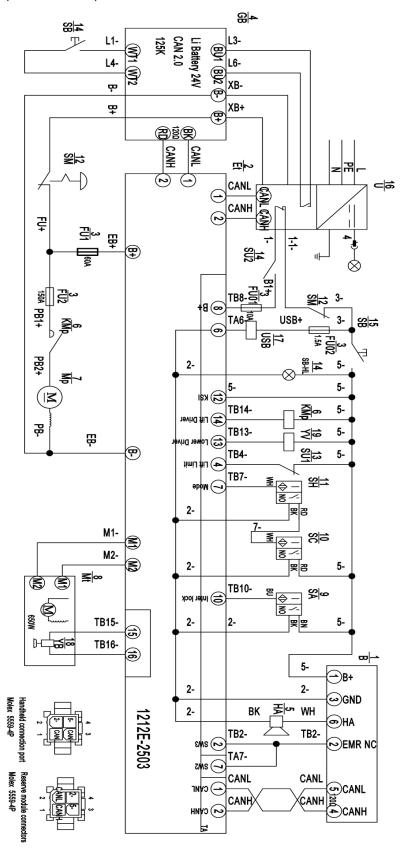


Fig 7: Electrical diagram (manual steering) 12ES-XN (EN1175:2020)

Table 6: Explanation of Electrical Symbols

| Code | Item               | Code | Item                        | Code | Item                    |
|------|--------------------|------|-----------------------------|------|-------------------------|
| В    | tiller             | Mt   | Traction motor              | SB   | Button switch           |
| Et   | controller         | SA   | Inter lock                  | U    | Charger                 |
| FU   | Fuse               | SC   | Lifting speed limit switch  | USB  | USB                     |
| GB   | Battery            | SH   | Steering speed limit switch | YB   | Electromagnetic brake   |
| HA   | Horn               | SM   | DC power switch             | YV   | Lowering solenoid valve |
| KMp  | Oil pump contactor | SU1  | Height limit microswitch    |      |                         |
| Мр   | Pump motor         | SU2  | Safety switch               |      |                         |

# 7-3. Schematic diagram of braking system

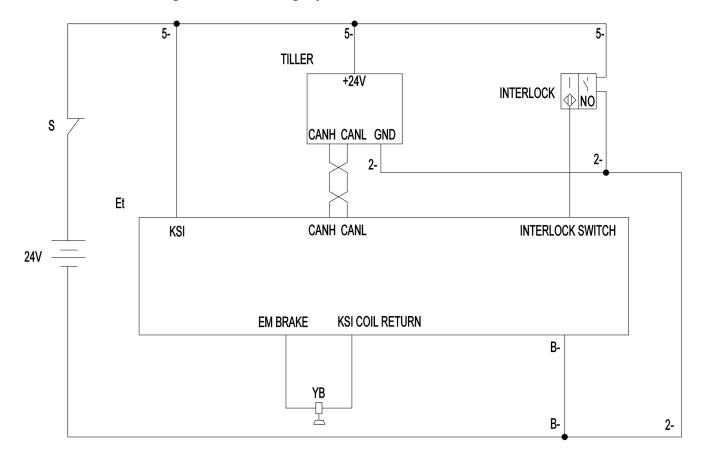


Fig 8: Schematic diagram

# 8 Charger

## 8-1 Lithium battery charger

## 8-1-1 Lithium battery charger introduction

WT2425ZMB type charger, this charger is an efficient, fast, small-sized, floor-standing charging device with CAN communication. The charger adopts two-phase AC 220V voltage input and adopts forced air cooling. It has input over-voltage, under-voltage, output over-voltage, under-voltage, over-current, output short-circuit, fan failure protection functions, and meets RoHS and CE requirements

## 8-1-2 Technical parameters of lithium battery charger

| Input Volts | Input Current | Power Factor | Overall    | Rated output | Rated output |
|-------------|---------------|--------------|------------|--------------|--------------|
| (VAC)       | ( <b>A</b> )  |              | efficiency | volts (V)    | current (A)  |
| 220±15%     | ≤9            | ≥0.9         | ≥93%       | 24±0.5       | 25±0.5       |
| VAC         |               |              |            |              |              |

- A, Input to the chassis Withstand voltage AC2000V, Leakage current <20mA;
- B. Output to case Withstand voltage AC1000V, Leakage current <20mA;
- C. Input to output Withstand voltage AC2000V, Leakage current <20mA;
- D. Insulation resistance test. The input is not less than 20MQ/DC 500V,

## 8-1-3 Lithium battery charging programs and instructions

Use according to the table below to avoid exceeding the specified usage requirements, otherwise the product may be damaged.

|           | Maximum Continuous<br>Discharge Current | 100A     |                          |
|-----------|---|----------|--------------------------|
| discharge | Maximum Pulse Discharge                 | 150A     | Do not exceed 10 seconds |
|           | Current                                 | 200A     | Do not exceed 3 seconds  |
|           | Discharge cut-off voltage               | ≥22V     |                          |
|           | Standard charging current               | 20A      |                          |
| charge    | Maximum charge current                  | 30A      | 0.5C                     |
|           | Charging Voltage                        | 28~29.6V |                          |

# Charge the battery:

- 1) Lithium-ion batteries can only be charged using an approved charger within the allowable temperature range.
- 2) The storage time of forklift trucks without battery compensation charging shall not exceed 24 weeks.
- 3) Improper connector plugs for industrial forklift trucks or battery chargers for use with lithium ion batteries may damage the battery connectors.
- 4) Operate lithium ion batteries only with appropriate forklift trucks and battery chargers.
- 5) Batteries can only be charged, repaired or replaced by trained personnel. These instructions and those of the battery manufacturer must be observed when performing these operations.

# 8.1.4Lithium battery charger indicator light description

| Indicator label                  | >80%   |                     |
|----------------------------------|--|---------------------|
| No-load indication               | Red green lights flashing alternately                  |                     |
| Battery indicator                | Red light flashes at 1s interval and                   |                     |
|                                  | the battery power is less than 80%.                    |                     |
|                                  | Yellow light flashes at 1s interval,                   |                     |
|                                  | battery power > 80%;                                   |                     |
|                                  | Green light flashes at 1s interval, battery power 100% |                     |
| Error indication                 | Overvoltage ( current ) failure                        | red green red       |
|                                  | Over temp or under temp                                | red green red green |
|                                  | Charger overheating                                    | green red           |
|                                  | Output under voltage                                   | red green           |
|                                  | Input AC anomaly                                       | Input AC anomaly    |
|                                  | Composite error  | green red green     |
| Fully charge shutdown indication | Green light is always on                               |                     |

# 8.1.5Lithium battery charger maintenance

- 1. In daily use, pay attention to cleaning the dust on the charger. After charging, put the power cord in place.
- 2. Pay attention to the use environment of the charger, try to avoid using the charger in harsh environments such as high temperature and high humidity

## 8.1.6 Troubleshooting

| • |   |
|---|---|
| Fault                                   | Explanation   |
| No power                                | Check whether the AC input is correctly connected and the power cord is damaged.  |
| Can't charge                            | Check whether the B+ and B-wires of the charger are connected properly  |
| Low Output Voltage at<br>Charge         | Check that the CAN bus of the module is properly connected to the control PCB board, otherwise contact the manufacturer for after-sales service support |
| Low Output Current at<br>Charge         | Check that the CAN bus of the module is properly connected to the control PCB board, otherwise contact the manufacturer for after-sales service support |

# Charger removal/installation

- 1 Remove the cover to access the drive motor controller.
- 2 Turn off the key switch and emergency stop switch.
- 3 Disconnect the charger AC power cord
- 4 Disconnect the charger control harness
- 5 Disconnect charger B+ and B-
- 6 Remove the fixing screws of the charger and take out the charger. Perform the above steps in reverse order to install the charger.